

ECE 2025 Problem Set #9 Solution

9.1 a) use the sampling property of impulses

$$\delta(t-3.5) = \begin{cases} 1, & t=3.5 \\ 0, & \text{else} \end{cases}$$

and L'Hôpital's rule

Using L'Hôpital's rule, we have

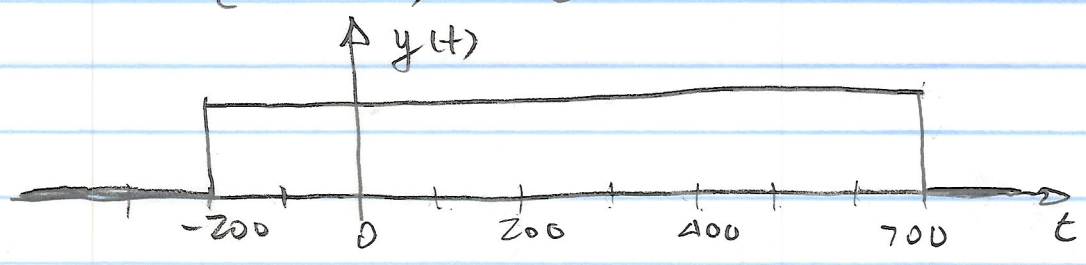
$$\begin{aligned} & \lim_{t \rightarrow 3.5} \frac{\sin(13\pi(t-3.5))}{\sin(\pi(t-3.5))} \\ &= \lim_{t \rightarrow 3.5} \frac{\cos(13\pi(t-3.5)) \cdot 13\pi}{\cos(\pi(t-3.5)) \cdot \pi} = 13 \end{aligned}$$

hence

$$\begin{aligned} x(t) &= \frac{\sin(13\pi(t-3.5)) \delta(t-3.5)}{\sin(\pi(t-3.5))} \\ &= 13 \delta(t-3.5) \end{aligned}$$

b) use property of impulse $\int_{-\infty}^{\infty} \delta(t) dt = 1$

$$\begin{aligned} y(t) &= \int_{-200}^{700} 3.3 \delta(\lambda-t) d\lambda \\ &= \begin{cases} 3.3, & -200 \leq t \leq 700 \\ 0, & \text{else} \end{cases} \end{aligned}$$



c) Use chain rule of derivatives and sampling property of impulses.

Let

$$\begin{aligned}
 x(t) &= \frac{d}{dt} \left\{ 0.7 \cos\left(\frac{1}{2}\pi t\right) u(t-6) \right\} \\
 &= 0.7 \cos\left(\frac{1}{2}\pi t\right) \frac{d}{dt} \{u(t-6)\} \\
 &\quad + \frac{d}{dt} \left\{ 0.7 \cos\left(\frac{1}{2}\pi t\right) \right\} u(t-6) \\
 &= 0.7 \cos\left(\frac{1}{2}\pi t\right) \delta(t-6) \\
 &\quad - 0.35\pi \sin\left(\frac{1}{2}\pi t\right) u(t-6)
 \end{aligned}$$

Then

$$z(t) = x(t) * \delta(t-0.5)$$

$$\begin{aligned}
 &= x(t-0.5) \\
 &= 0.7 \cos\left(\frac{1}{2}\pi(t-0.5)\right) \delta(t-0.5-6) \\
 &\quad - 0.35\pi \sin\left(\frac{1}{2}\pi(t-0.5)\right) u(t-0.5-6) \\
 &= 0.7 \cos\left(\frac{1}{2}\pi(6)\right) \delta(t-6.5) \\
 &\quad - 0.35\pi \sin\left(\frac{1}{2}\pi(t-0.5)\right) u(t-6.5) \\
 &= -0.7 \delta(t-6.5) \\
 &\quad - 0.35\pi \sin\left(\frac{1}{2}\pi(t-0.5)\right) u(t-6.5)
 \end{aligned}$$

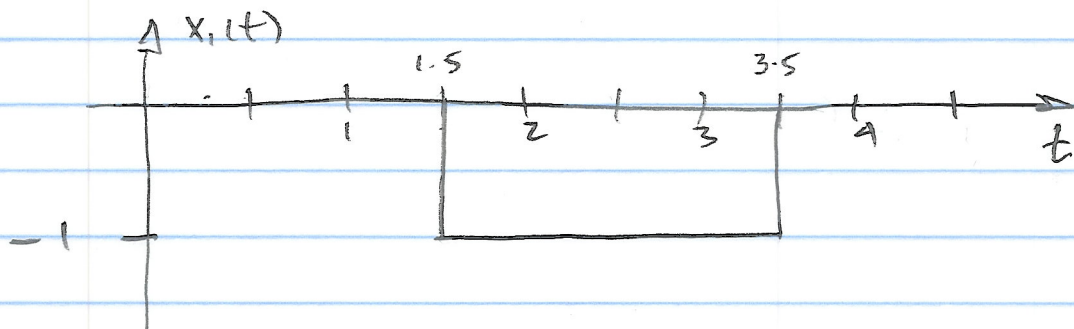
d) use sampling property of impulses. 3/

$$\begin{aligned} s(t) &= \int_{-\infty}^{\infty} 9e^{-0.4\tau^2} \delta\left(\tau - \frac{1}{2}t\right) d\tau \\ &= 9e^{-0.4\left(\frac{1}{2}t\right)^2} \\ &= 9e^{-0.1t^2} \end{aligned}$$

2a) use linearity and the property

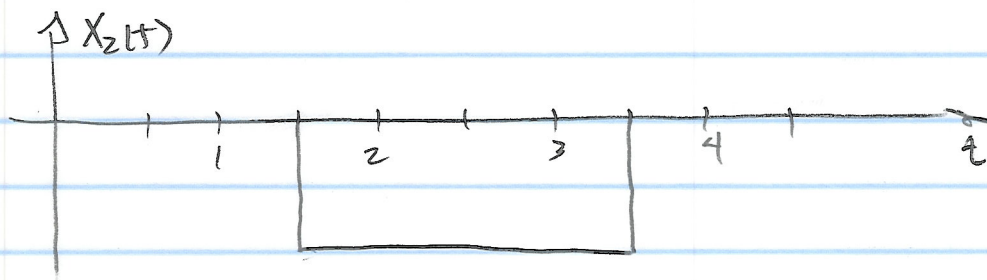
$$x(t) * \delta(t-t_0) = x(t-t_0)$$

$$\begin{aligned} x_1(t) &= u(t-1/2) * [\delta(t-3) - \delta(t-1)] \\ &= u(t-1/2) * \delta(t-3) - u(t-1/2) * \delta(t-1) \\ &= u(t-3.5) - u(t-1.5) \\ &= -u(t-1.5) + u(t-3.5) \end{aligned}$$



b) use commutative property of convolution and the property
 $x(t) * \delta(t-t_0) = x(t-t_0)$

$$\begin{aligned} x_2(t) &= \delta(t-1/2) * [u(t-3) - u(t-1)] \\ &= [u(t-3) - u(t-1)] * \delta(t-1/2) \\ &= -u(t-1.5) + u(t-3.5) \end{aligned}$$



c) convolution of a unit step and rectangular pulse

$$x_3(t) = u(t-1/2) * [u(t-3) - u(t-1)]$$

Note

$$\begin{aligned} &= \int_{-\infty}^{\infty} [u(\tau-3) - u(\tau-1)] u(t-\tau-1/2) d\tau \\ &= - \int_1^3 u(t-\tau-1/2) d\tau \end{aligned}$$

Now consider ranges of t

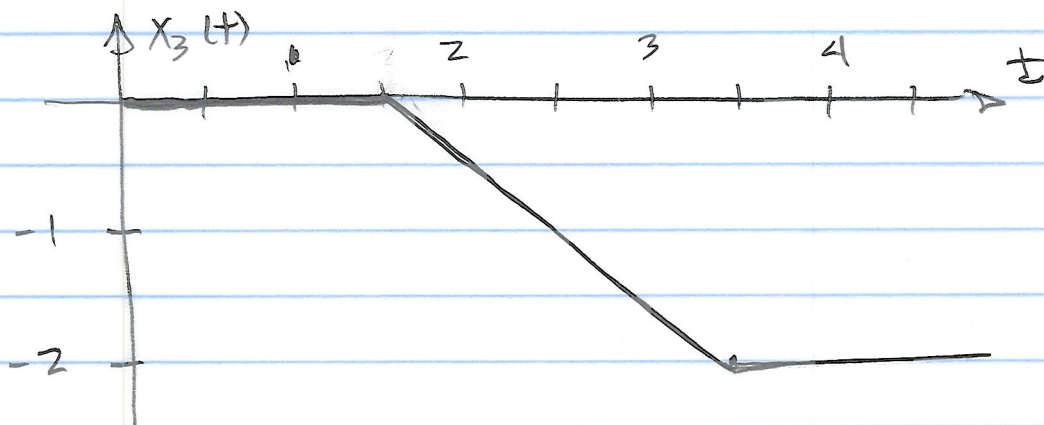
For $t < 1.5$, $X_3(t) = 0$

For $1.5 \leq t \leq 3.5$

$$\begin{aligned} X_3(t) &= -\int_1^{t-1/2} d\tau = -\tau \Big|_1^{t-1/2} \\ &= -t + 1/2 + 1 \\ &= 1.5 - t \end{aligned}$$

For $t > 3.5$

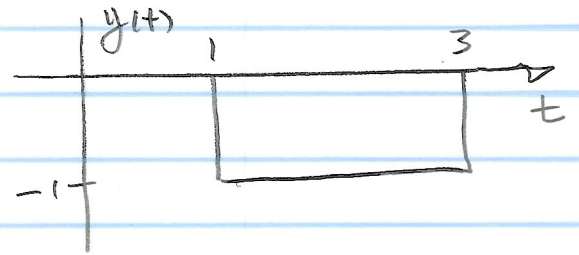
$$X_3(t) = -\int_1^3 d\tau = -2$$



$$X_3(t) = \begin{cases} 0, & t < 1.5 \\ 1.5 - t, & 1.5 \leq t \leq 3.5 \\ -2, & t > 3.5 \end{cases}$$

d) convolution of two rectangular pulses.

$$\text{let } y(t) = u(t-3) - u(t-1)$$



$$\text{Then } x_4(t) = y(t) * y(t)$$

$$= \int_{-\infty}^{\infty} y(\tau) y(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} [u(\tau-3) - u(\tau-1)] \times [u(t-\tau-3) - u(t-\tau-1)] d\tau$$

$$= \int_1^3 [u(t-\tau-1) - u(t-\tau-3)] d\tau$$

Consider range of t

$$\text{For } t \leq 2, \quad x_4(t) = 0$$

$$\text{For } 2 \leq t \leq 4$$

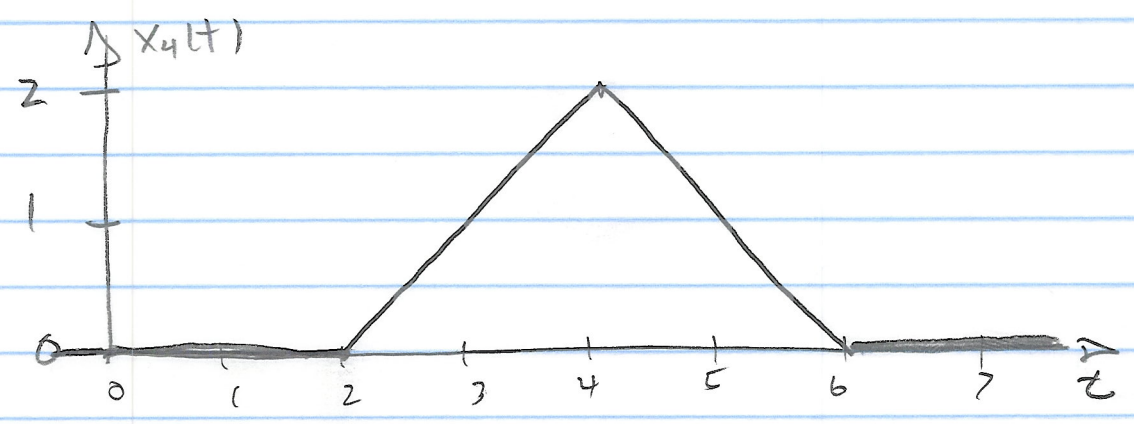
$$x_4(t) = \int_1^{t-1} d\tau = t-1-1 = t-2$$

For $4 \leq t \leq 6$

$$x_4(t) = \int_{t-3}^3 d\tau = 3 - (t-3) = 6 - t$$

For $t \geq 6$ $x_4(t) = 0$

$$x_4(t) = \begin{cases} 0, & t \leq 2 \\ t-2, & 2 \leq t \leq 4 \\ 6-t, & 4 \leq t \leq 6 \\ 0, & t \geq 6 \end{cases}$$



9.3a) Use linearity and superposition,
to write

$$x(t) * h(t) = x(t) * h_1(t) + x(t) * h_2(t)$$

where

$$h(t) = h_1(t) + h_2(t)$$

and

$$h_1(t) = \pi \delta(t - 2.5)$$

$$h_2(t) = \frac{1}{2} u(t - 3.5)$$

1.

$$x(t) * h_1(t)$$

$$= x(t) * \pi \delta(t - 2.5)$$

$$= \pi x(t - 2.5)$$

$$= \frac{\pi}{3} e^{-3(t-3.5)} [u(t-2.5) - u(t-3)]$$

2.

$$x(t) * h_2(t)$$

$$= \frac{1}{3} e^{-3(t-1)} [u(t) - u(t-1/2)] * \frac{1}{2} u(t-3.5)$$

$$= \frac{1}{6} \int_{-\infty}^{\infty} e^{-3(\tau-1)} [u(\tau) - u(\tau-1/2)]$$

$$* u(t-\tau-3.5) d\tau$$

$$= \frac{1}{6} \int_0^{1/2} e^{-3(\tau-1)} u(t-\tau-3.5) d\tau$$

we now break into regions of t .

Case 1: $t < 3.5$, $x(t) * h_1(t) = 0$

Case 2: $3.5 < t < 4$

$$\begin{aligned}
 x(t) * h_2(t) &= \frac{1}{6} \int_0^{t-3.5} e^{-3(\tau-1)} d\tau \\
 &= \frac{e^3}{6} \int_0^{t-3.5} e^{-3\tau} d\tau \\
 &= -\frac{e^3}{18} e^{-3\tau} \Big|_0^{t-3.5} \\
 &= \frac{e^3}{18} (1 - e^{-3(t-3.5)})
 \end{aligned}$$

Case 3: $t > 4$

$$\begin{aligned}
 x(t) * h_2(t) &= \frac{1}{6} \int_0^{1/2} e^{-3(\tau-1)} d\tau \\
 &= \frac{e^3}{6} \int_0^{1/2} e^{-3\tau} d\tau \\
 &= -\frac{e^3}{18} e^{-3\tau} \Big|_0^{1/2} \\
 &= \frac{e^3}{18} (1 - e^{-3/2})
 \end{aligned}$$

Hence,

$$x(t) * h_2(t) = \begin{cases} 0 & , t < 3.5 \\ \frac{e^3}{18} (1 - e^{-3(t-3.5)}) & , 3.5 \leq t \leq 4 \\ \frac{e^3}{18} (1 - e^{-3/2}) & , t > 4 \end{cases}$$

Finally, $x(t) * h(t) = x(t)h_1(t) - x(t)h_2(t)$
 with $x(t)h_1(t)$ and $x(t) * h_2(t)$
 given above.

b) Consider each term separately

$$\begin{aligned} \lim_{t \rightarrow \infty} x(t) * h_1(t) &= \lim_{t \rightarrow \infty} \frac{\pi}{3} e^{-3(t-3.5)} [u(t-2.5) - u(t-3)] \\ &= 0 \end{aligned}$$

$$\begin{aligned} \lim_{t \rightarrow \infty} x(t) * h_2(t) &= \frac{e^3}{18} (1 - e^{-3/2}) \end{aligned}$$

Hence

$$\begin{aligned} \lim_{t \rightarrow \infty} x(t) * h(t) &= -\frac{e^3}{18} (1 - e^{-3/2}) \end{aligned}$$

9.4a) Set $x(t) = u(t)$ and solve the integral.

$$y(t) = \int_2^4 e^{2\tau-6} u(t-\tau) d\tau$$

Case 1: $t < 2$ $y(t) = 0$

Case 2: $2 \leq t \leq 4$

$$\begin{aligned} y(t) &= \int_2^t e^{2\tau-6} d\tau \\ &= e^{-6} \int_2^t e^{2\tau} d\tau \\ &= e^{-6} \left. \frac{1}{2} e^{2\tau} \right|_2^t \\ &= \frac{e^{-6}}{2} (e^{2t} - e^4) \end{aligned}$$

Case 3: $t > 4$

$$\begin{aligned} y(t) &= \int_2^4 e^{2\tau-6} d\tau \\ &= e^{-6} \left. \frac{1}{2} e^{2\tau} \right|_2^4 \\ &= \frac{e^{-6}}{2} (e^8 - e^4) \\ &= \frac{e^2 - e^{-2}}{2} \end{aligned}$$

Hence, step response is

$$y(t) = \begin{cases} 0 & , t < 2 \\ \frac{e^{-b}}{2} (e^{2t} - e^4) & , 2 \leq t \leq 4 \\ \frac{e^2 - e^{-2}}{2} & , t > 4 \end{cases}$$

b) Set $x(t) = \delta(t)$ and solve the integral

$$h(t) = \int_2^4 e^{2\tau - b} \delta(t - \tau) d\tau$$

Case 1: $t < 2$, $h(t) = 0$

Case 2: $2 \leq t \leq 4$, $h(t) = e^{2t - b}$

Case 3: $t > 4$, $h(t) = 0$

From part a), we have

$$\frac{dy(t)}{dt} = \begin{cases} 0 & , t < 2 \\ e^{2t - b} & , 2 \leq t \leq 4 \\ 0 & , t > 4 \end{cases}$$

∴ impulse resp. is derivative of step resp.

c) Test for bounded-input
bounded-output stability.

$$\int_{-\infty}^{\infty} |h(t)| dt < \infty$$

$$\int_{-\infty}^{\infty} |h(t)| dt = \int_2^4 e^{2t-6} dt$$

$$= e^{-6} \frac{1}{2} e^{2t} \Big|_2^4$$

$$= \frac{e^{-6}}{2} (e^8 - e^4)$$

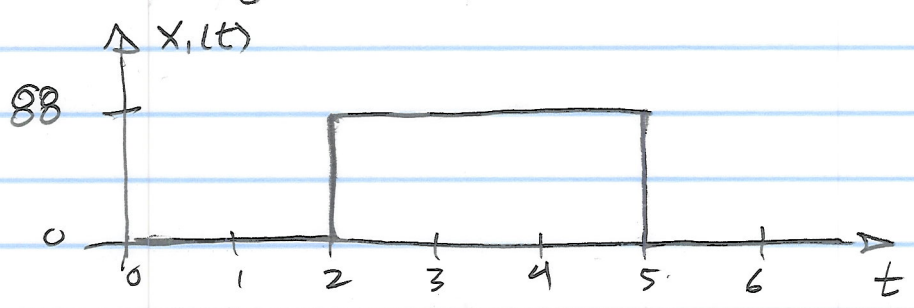
$$= \frac{e^2 - e^{-2}}{2} < \infty$$

∴ system is stable

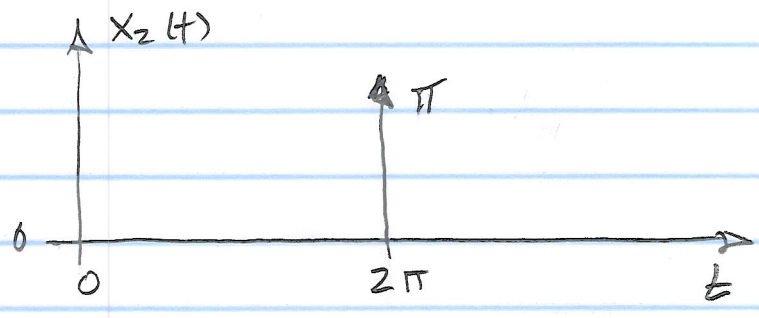
d) System is causal if
 $h(t) = 0, t < 0$

From part b), this is clearly
the case, since $h(t) = 0, t < 2$

9.5a) straight forward.

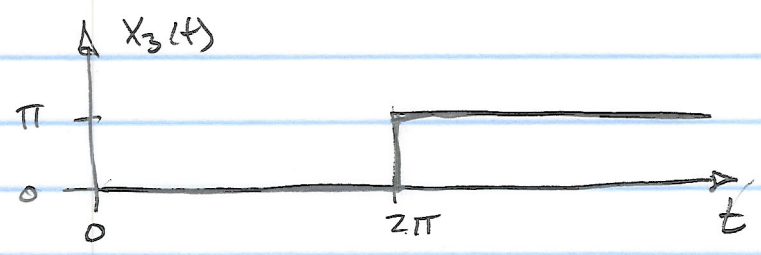


b) straight forward



c) Integral of impulse gives a step

$$X_3(t) = \pi u(t - 2\pi)$$



d) shift right $e^{-t}u(t)$ by 4.

