

GEORGIA INSTITUTE OF TECHNOLOGY
SCHOOL of ELECTRICAL & COMPUTER ENGINEERING
FINAL EXAM

DATE: 2-May-05

COURSE: ECE-2025

NAME: _____ GT #: _____
LAST, FIRST _____ (ex: gtz123a)

Recitation Section: Circle the date & time when your **Recitation Section** meets (not Lab):

L05:Tues-Noon (Chang)	L06:Thur-Noon (Ingram)		
L07:Tues-1:30pm (Chang)	L08:Thurs-1:30pm (Zhou)		
L01:M-3pm (Williams)	L09:Tues-3pm (Casinovi)	L02:W-3pm (Juang)	L10:Thur-3pm (Zhou)
L03:M-4:30pm (Casinovi)	L11:Tues-4:30pm (Casinovi)	L04:W-4:30pm (Juang)	GTSav: (Moore)

- Write your name on the front page ONLY. **DO NOT** unstaple the test.
- Closed book, but a calculator is permitted.
- One page ($8\frac{1}{2}'' \times 11''$) of **HAND-WRITTEN** notes permitted. OK to write on both sides.
- **JUSTIFY** your reasoning clearly to receive partial credit.
Explanations are also required to receive full credit for any answer.
- You must write your answer in the space provided on the exam paper itself.
Only these answers will be graded. Circle your answers, or write them in the boxes provided.
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<i>Problem</i>	<i>Value</i>	<i>Score</i>
1	30	
2	30	
3	30	
4	30	
5	30	
6	30	
7	30	

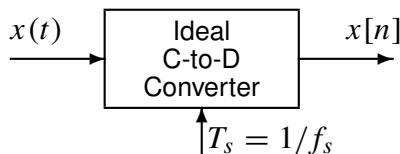
PROBLEM sp-05-F.1:

For each part, pick a correct frequency¹ from the list and enter its letter in the answer box²:

Write a brief explanation of your answers to receive any credit.

- (a) If the output from an ideal C/D converter is $x[n] = 33 \cos(0.5\pi n)$, and the sampling rate is 2000 samples/sec, then determine one possible value of the input frequency of $x(t)$:

ANS =

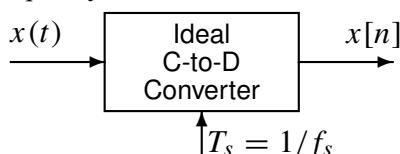


Frequency

- (a) 8000 Hz
- (b) 4000 Hz
- (c) 2000 Hz
- (d) 1600 Hz
- (e) 1200 Hz
- (f) 1000 Hz
- (g) 800 Hz
- (h) 500 Hz
- (i) 400 Hz

- (b) If the output from an ideal C/D converter is $x[n] = 33 \cos(0.5\pi n)$, and the input signal $x(t)$ defined by: $x(t) = 33 \cos(3000\pi t)$ then determine one possible value of the sampling frequency of the C-to-D converter:

ANS =



- (c) Determine the Nyquist rate for sampling the signal $x(t)$ defined by:
 $x(t) = (A - B \cos(800\pi t)) \sin(1200\pi t)$.

ANS =

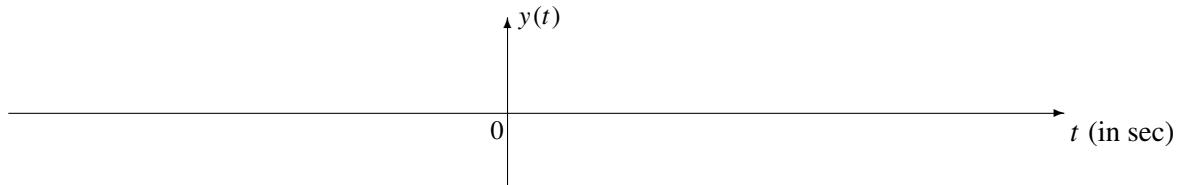
¹Some questions have more than one answer, but you only need to pick one correct answer from the list.

²It is possible to use an answer more than once.

PROBLEM sp-05-F.2:

The impulse response, $h(t)$, of a continuous-time linear, time-invariant system is: $h(t) = -7\delta(t) + A\delta(t - \Delta)$

- (a) Find the output of the system, $y(t)$, when the input is $x(t) = u(t)$, $A = 7$, and $\Delta = 0.025$. Give your answer as a plot on the axes below. Label your plot carefully.

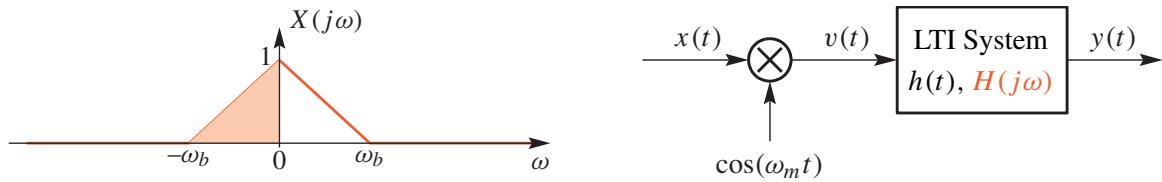


- (b) Find the output of the system, $y(t)$, when the input is $x(t) = \cos(100\pi t)$, $A = -7$, and $\Delta = 0.025$. Express your answer as a single sinusoid.

- (c) Now assume that the input signal is $x(t) = \cos(100\pi t)u(t)$, i.e., a one-sided sinusoid that is zero for $t < 0$. Find values for A and Δ that will produce an output $y(t)$ that is **exactly three and half periods** of a 50-Hz sinusoid, and zero thereafter.

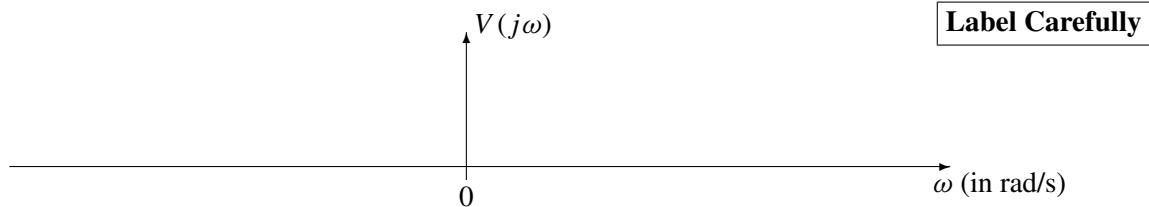
PROBLEM sp-05-F.3:

The transmitter system below involves a multiplier followed by a filter:



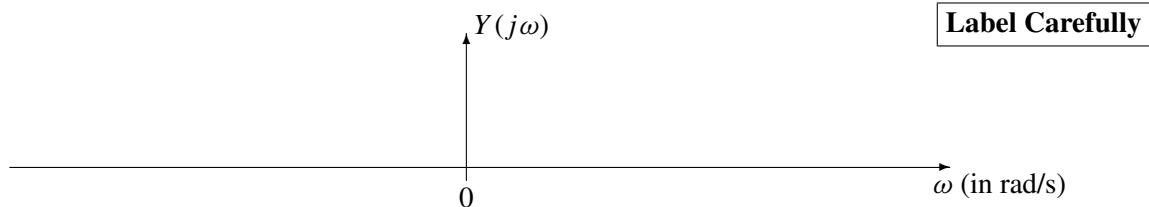
The Fourier transform of the input is $X(j\omega)$. For all parts below, assume that $\omega_m = 100\pi$, and $\omega_b = 20\pi$.

- (a) Make a sketch of $V(j\omega)$, the Fourier transform of $v(t)$, when the input is $X(j\omega)$ shown above.



(b) If the filter is an ideal filter defined by $H(j\omega) = \begin{cases} 0 & |\omega| < 100\pi \\ j & \omega \geq 100\pi \\ -j & \omega \leq -100\pi \end{cases}$

Make a sketch of $Y(j\omega)$, the Fourier transform of $y(t)$, when the input is $X(j\omega)$ shown above.



- (c) Now change the input to be $x(t) = A \cos(\omega_c t + \varphi)$. Determine the values of ω_c , φ , and A so that the output signal is $y(t) = \cos(110\pi t)$. Note: Use $\omega_m = 100\pi$ as above and $H(j\omega)$ from part (b).

PROBLEM sp-05-F.4:

The diagram in Fig. 1 depicts a *cascade connection* of two linear time-invariant systems, i.e., the output of the first system is the input to the second system, and the overall output is the output of the second system.

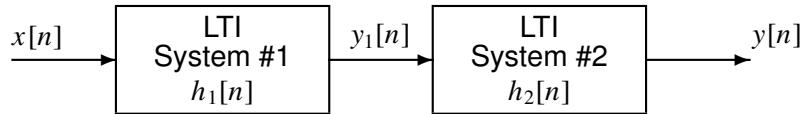


Figure 1: Cascade connection of two discrete-time LTI systems.

Suppose that System #1 is an IIR filter described by the system function:

$$H_1(z) = \frac{9z^{-2} - 9z^{-3}}{1 - 2z^{-1}}$$

but System #2 is unknown.

- (a) Determine whether or not System #1 is stable. Give a reason to support your answer.
- (b) When the input signal $x[n]$ is a **unit-step** signal, determine the output of the first system, $y_1[n]$.
- (c) When the input signal $x[n]$ is a **unit-impulse** signal, the output $y[n]$ of the overall cascaded system is:

$$y[n] = \delta[n - 2]$$

From this information, determine the system function $H_2(z)$ for the second system. *Simplify the expression for $H_2(z)$.*

PROBLEM sp-05-F.5:

In each case, make a sketch of the plot that MATLAB will produce. Label your sketches carefully.

Hint: Convert the MATLAB code to an equivalent mathematical function or operation to make the sketch.

(a) `xn = [1, zeros(1,4)];
yn = filter([1,-1], [1,2], xn);
stem(0:4, yn)`

(b) `ww = -pi:pi/200:pi;
[HH,ww] = freekz([13,13], [1,-0.5], ww);
plot(ww, abs(HH))`

(c) `tt = 1e-12 + 0.02*(-100:100); %-avoid divide by zero
ht = sin(pi*tt)./tt/2;
plot(tt, ht)`

PROBLEM sp-05-F.6:

In each of the following cases, determine the (inverse or forward) Fourier transform. The following Fourier transform pair will be needed for some parts:

$$x(t) = e^{-t^2} \quad \longleftrightarrow \quad X(j\omega) = \sqrt{2\pi} e^{-\omega^2/4}$$

Give your answer as a plot, or a simple formula.

(a) Find $x(t)$ when $X(j\omega) = 14 \cos(3\omega)$.

(b) Find $S(j\omega)$ when $s(t) = \left\{ \frac{d}{dt} e^{-t^2} \right\} \delta(t - 3)$.

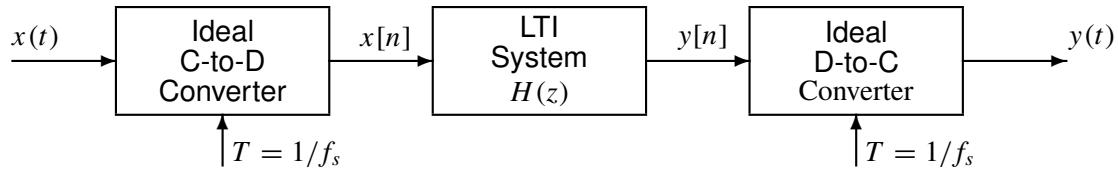
(c) Find $R(j\omega)$ when $r(t) = e^{-9t^2}$.

(d) Find $H(j\omega)$ when $h(t) = u(t - 5)u(8 - t)$.

(e) The convolution $y(t) = \frac{\sin(13\pi t)}{\pi t} * \left\{ \sum_{n=-\infty}^{\infty} \delta(t - n/8) \right\}$ evaluates to a constant, i.e., $y(t) = y_0$.

Find the value of y_0 .

PROBLEM sp-05-F.7:



In all parts below, the sampling rates of the C-to-D and D-to-C converters **are equal to** $f_s = 180$ samples/sec, and the LTI system is an IIR filter with two poles at $0.9e^{\pm j\pi/3}$, and two zeros at $e^{\pm j\pi/3}$, i.e., the system function is $H(z) = \frac{(1 - q_1 z^{-1})(1 - q_2 z^{-1})}{(1 - p_1 z^{-1})(1 - p_2 z^{-1})}$, where $p_{1,2}$ are the poles and $q_{1,2}$ are the zeros.

- (a) Determine the filter coefficients of the IIR filter and fill in the IIR difference equation below.

$$y[n] = \boxed{} y[n-1] + \boxed{} y[n-2] + \boxed{} x[n] + \boxed{} x[n-1] + \boxed{} x[n-2]$$

- (b) Determine the DC response of the digital filter, i.e., the output $y[n]$ when the input is $x[n] = 1$.

- (c) If the input signal is a sinusoid of the form $x(t) = \cos(2\pi f_0 t + \phi)$, and the sampling rates are $f_s = 180$ samples/sec, determine a value for the input frequency f_0 so that the output signal is zero. **Explain.**

$$f_0 = \boxed{} \text{ Hz}$$

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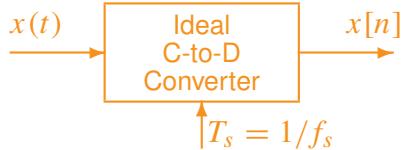
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PROBLEM sp-05-F.1:

For each part, pick a correct frequency¹ from the list and enter its letter in the answer box²:

Write a brief explanation of your answers to receive any credit.

- (a) If the output from an ideal C/D converter is $x[n] = 33 \cos(0.5\pi n)$, and the sampling rate is 2000 samples/sec, then determine one possible value of the input frequency of $x(t)$:



$$\hat{\omega} = 0.5\pi \text{ rads}, f_s = 2000 \text{ Hz}$$

$$\hat{\omega} = \frac{2\pi f}{f_s} + 2\pi\ell \Rightarrow f = \frac{\hat{\omega} - 2\pi\ell}{2\pi} f_s$$

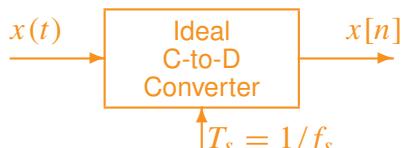
$$\text{For } \ell = 0, f = \left(\frac{0.5\pi}{2\pi}\right) 2000 = 500 \text{ Hz}$$

ANS = (h)

Frequency

- (a) 8000 Hz
- (b) 4000 Hz
- (c) 2000 Hz
- (d) 1600 Hz
- (e) 1200 Hz
- (f) 1000 Hz
- (g) 800 Hz
- (h) 500 Hz
- (i) 400 Hz

- (b) If the output from an ideal C/D converter is $x[n] = 33 \cos(0.5\pi n)$, and the input signal $x(t)$ defined by: $x(t) = 33 \cos(3000\pi t)$ then determine one possible value of the sampling frequency of the C-to-D converter:



$$\hat{\omega} = \frac{2\pi f}{f_s} + 2\pi\ell \quad (f \text{ can be } \pm)$$

$$\Rightarrow f_s = \frac{\pm 2\pi f}{\hat{\omega} - 2\pi\ell} = \frac{\pm 3000\pi}{0.5\pi - 2\pi\ell} = \frac{\pm 6000}{1 - 4\ell} \text{ Hz}$$

$$\text{For } \ell = 0, f_s = 6000 \text{ Hz}$$

$$\text{For } \ell = -1, \text{ numerator} = 6000, f_s = 1200 \text{ Hz}$$

ANS = (e)

$$\text{For } \ell = +1, +4, \text{ numerator} = -6000, f_s = 2000, 400 \text{ Hz}$$

ANS = (c),(i)

- (c) Determine the Nyquist rate for sampling the signal $x(t)$ defined by:
 $x(t) = (A - B \cos(800\pi t)) \sin(1200\pi t)$.

$$y(t) = \left(A - \frac{B}{2}e^{j800\pi t} - \frac{B}{2}e^{-j800\pi t}\right) \left(\frac{1}{2j}e^{j1200\pi t} - \frac{1}{2j}e^{-j1200\pi t}\right)$$

\Rightarrow highest frequency in $x(t)$ is $\omega_{\max} = 800\pi + 1200\pi = 2000\pi$ rad/s.

$$f_{\max} = 1000 \text{ Hz} \implies f_s > 2f_{\max} = f_{\text{Nyquist}} = 2000 \text{ Hz}$$

ANS = (c)

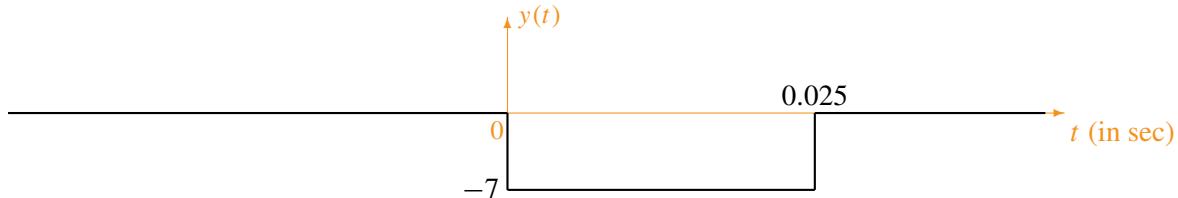
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PROBLEM sp-05-F.2:

The impulse response, $h(t)$, of a continuous-time linear, time-invariant system is: $h(t) = -7\delta(t) + A\delta(t - \Delta)$

- (a) Find the output of the system, $y(t)$, when the input is $x(t) = u(t)$, $A = 7$, and $\Delta = 0.025$. Give your answer as a plot on the axes below. Label your plot carefully.



$$\begin{aligned} y(t) &= x(t) * h(t) \\ &= -7u(t) + 7u(t - 0.025) \quad (\text{This is a rectangular pulse}) \end{aligned}$$

- (b) Find the output of the system, $y(t)$, when the input is $x(t) = \cos(100\pi t)$, $A = -7$, and $\Delta = 0.025$. Express your answer as a single sinusoid.

$$y(t) = 7\sqrt{2} \cos(100\pi t + 3\pi/4)$$

$$\begin{aligned} y(t) &= x(t) * h(t) = -7x(t) - 7x(t - 0.025) \\ &= -7 \cos(100\pi t) - 7 \cos(100\pi(t - 0.025)) \\ &= -7 \cos(100\pi t) - 7 \cos(100\pi t - 2.5\pi) \end{aligned}$$

Use Phasor Addition:

$$-7e^{j0} - 7e^{-j2.5\pi} = -7 + j7 = 7\sqrt{2} e^{+j3\pi/4}$$

- (c) Now assume that the input signal is $x(t) = \cos(100\pi t)u(t)$, i.e., a one-sided sinusoid that is zero for $t < 0$. Find values for A and Δ that will produce an output $y(t)$ that is *exactly three and half periods* of a 50-Hz sinusoid, and zero thereafter.

$$A = -7 \quad \Delta = 0.07 \text{ secs.}$$

100π rad/s is the same as 50 Hz \Rightarrow period = 1/50 secs.

3.5 periods \Rightarrow $3.5/50$ secs. = 0.07 secs.

Cancel the tail of $x(t)$ with the shifted version $x(t - \Delta)$

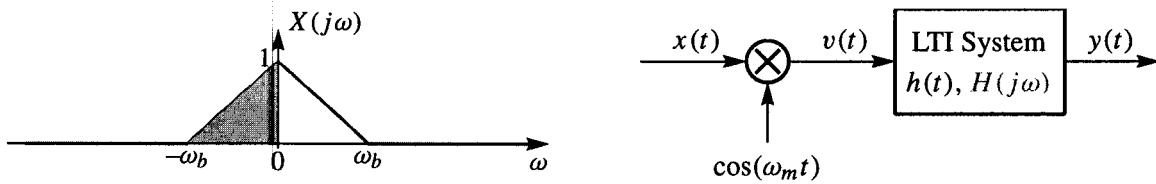
$$y(t) = x(t) * h(t) = -7x(t) + Ax(t - \Delta)$$

$$\text{Need } y(0.07) = 0 \Rightarrow -7x(0.07) + Ax(0) = 0$$

$$\text{Since } x(0) = 1 \text{ and } x(0.07) = \cos(100\pi(0.07)) = -1, \quad A = 7x(0.07) = -7$$

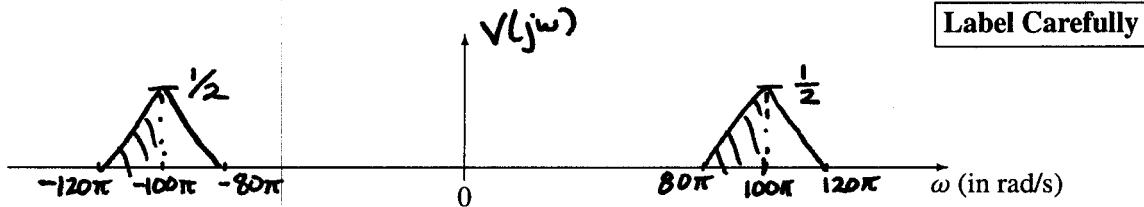
PROBLEM sp-05-F.3:

The transmitter system below involves a multiplier followed by a filter:



The Fourier transform of the input is $X(j\omega)$. For all parts below, assume that $\omega_m = 100\pi$, and $\omega_b = 20\pi$.

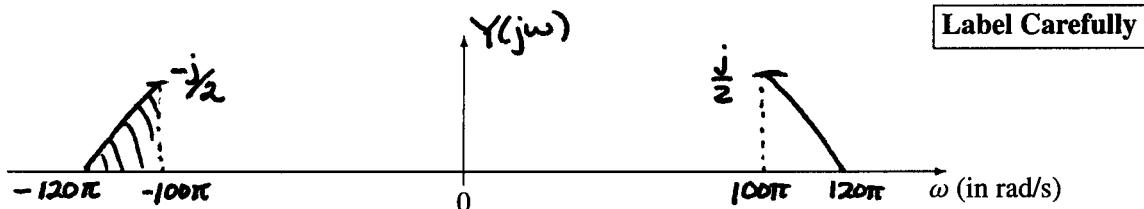
- (a) Make a sketch of $V(j\omega)$, the Fourier transform of $v(t)$, when the input is $X(j\omega)$ shown above.



$$V(j\omega) = \frac{1}{2} X(j(\omega - \omega_m)) + \frac{1}{2} X(j(\omega + \omega_m))$$

- (b) If the filter is an ideal filter defined by $H(j\omega) = \begin{cases} 0 & |\omega| < 100\pi \\ j & \omega \geq 100\pi \\ -j & \omega \leq -100\pi \end{cases}$ This is a HPF with phase

Make a sketch of $Y(j\omega)$, the Fourier transform of $y(t)$, when the input is $X(j\omega)$ shown above.



$$Y(j\omega) = H(j\omega) V(j\omega)$$

Since $H(j\omega) = 0$ for $|\omega| < 100\pi$, the spectrum components below 100π rad/s are eliminated.

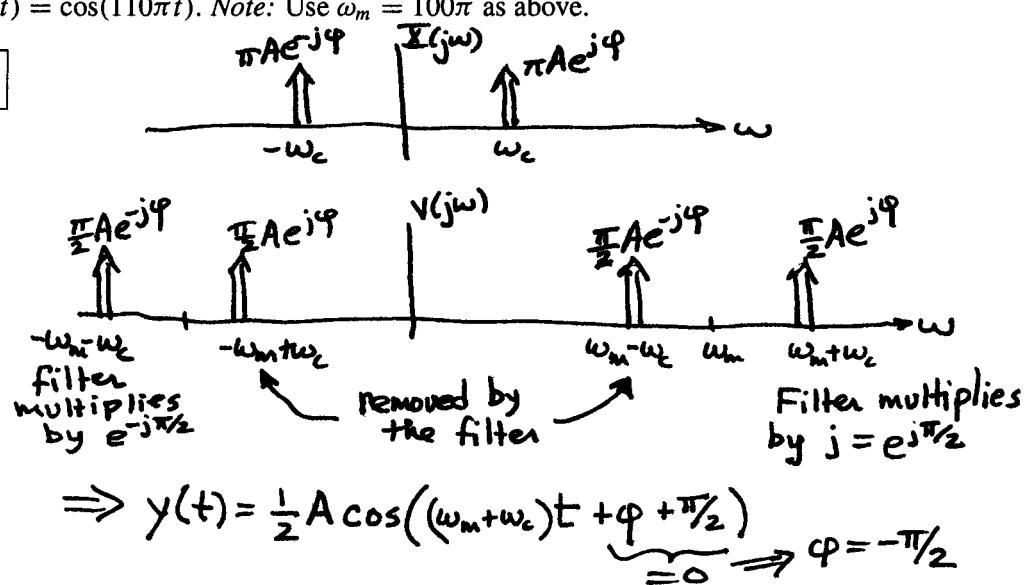
- (c) Now change the input to be $x(t) = A \cos(\omega_c t + \varphi)$. Determine the values of ω_c , φ , and A so that the output signal is $y(t) = \cos(110\pi t)$. Note: Use $\omega_m = 100\pi$ as above.

$$\omega_c = 10\pi$$

$$\varphi = -\pi/2$$

$$A = 2$$

$$\begin{aligned} \omega_m + \omega_c &= 110\pi \\ \Rightarrow \omega_c &= 110\pi - 100\pi \\ &= 10\pi \text{ rad/s} \end{aligned}$$



PROBLEM sp-05-F.4:

The diagram in Fig. 1 depicts a *cascade connection* of two linear time-invariant systems, i.e., the output of the first system is the input to the second system, and the overall output is the output of the second system.

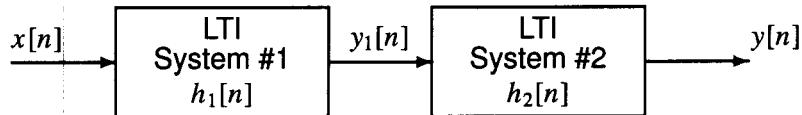


Figure 1: Cascade connection of two discrete-time LTI systems.

Suppose that System #1 is an IIR filter described by the system function:

$$H_1(z) = \frac{9z^{-2} - 9z^{-3}}{1 - 2z^{-1}}$$

but System #2 is unknown.

- (a) Determine whether or not System #1 is stable. Give a reason to support your answer.

$H_1(z)$ has one pole at $z=2$. Thus $h_1[n]$ acts like 2^n
 \therefore System #1 is unstable

- (b) When the input signal $x[n]$ is a *unit-step* signal, determine the output of the first system, $y_1[n]$.

$$x[n] = u[n] \Rightarrow X(z) = \frac{1}{1-z^{-1}}$$

$$\begin{aligned} Y_1(z) &= X(z) H_1(z) = \left(\frac{1}{1-z^{-1}} \right) \left(\frac{9z^{-2}(1-z^{-1})}{1-2z^{-1}} \right) \\ &= \frac{9z^{-2}}{1-2z^{-1}} \end{aligned}$$

$$\therefore y_1[n] = 9(2)^{n-2} u[n-2]$$

- (c) When the input signal $x[n]$ is a *unit-impulse* signal, the output $y[n]$ of the overall cascaded system is:

$$y[n] = \delta[n-2]$$

From this information, determine the system function $H_2(z)$ for the second system. *Simplify the expression for $H_2(z)$.*

$$y[n] = \delta[n-2] \Rightarrow Y(z) = z^{-2} \quad x[n] = \delta[n] \Rightarrow X(z) = 1$$

$$Y(z) = H_1(z) H_2(z) X(z)$$

$$H_2(z) = \frac{Y(z)}{H_1(z) X(z)} = \frac{z^{-2}}{\frac{9z^{-2}(1-z^{-1})}{1-2z^{-1}}} = \frac{1-2z^{-1}}{9(1-z^{-1})}$$

PROBLEM sp-05-F.5:

In each case, make a sketch of the plot that MATLAB will produce. Label your sketches carefully.

Hint: Convert the MATLAB code to an equivalent mathematical function or operation to make the sketch.

(a)

```
xn = [1,zeros(1,4)];
yn = filter([1,-1], [1,2], xn);
stem(0:4, yn)
```

Plot the solution of $y[n] = -2y[n - 1] + x[n] - x[n - 1]$ for $n = 0, 1, 2, 3, 4$. See the plot on the next page.

(b)

```
ww = -pi:pi/200:pi;
[HH,ww] = freekz([13,13], [1,-0.5], ww);
plot(ww, abs(HH))
```

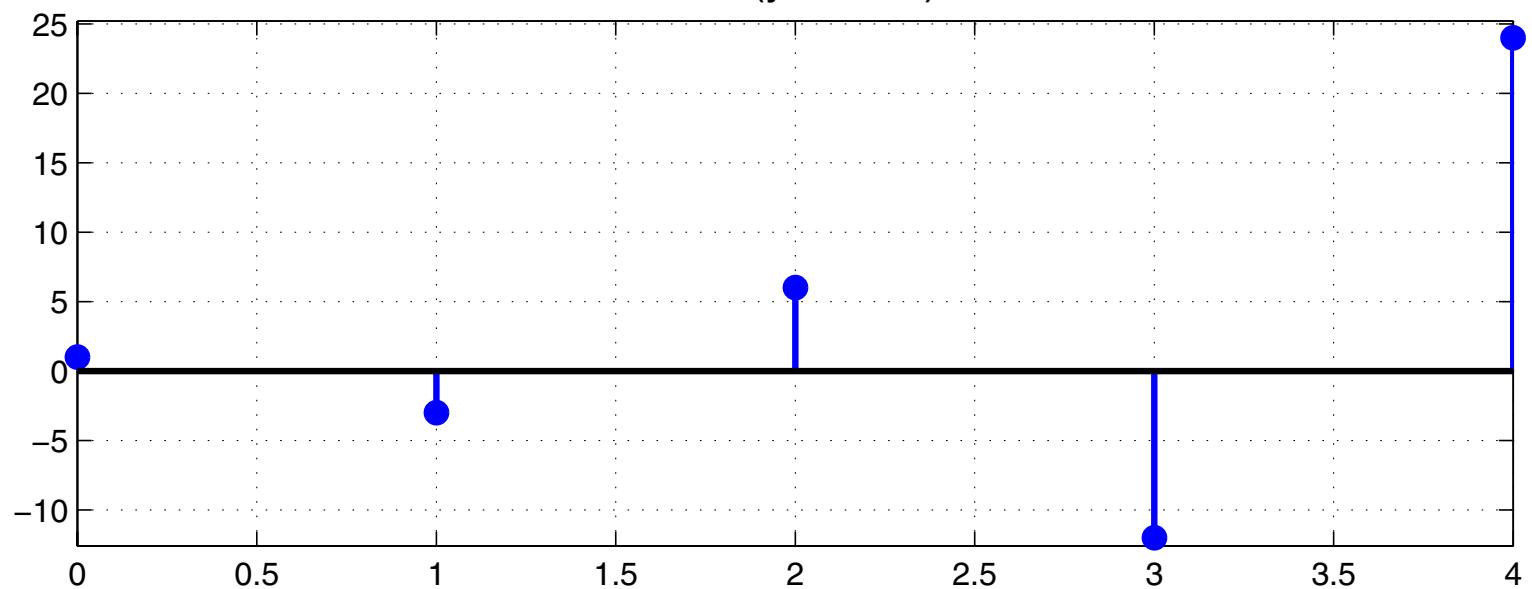
Plot $H(e^{j\omega}) = \frac{13 + 13e^{-j\hat{\omega}}}{1 - 0.5e^{-j\hat{\omega}}}$ for $-\pi \leq \omega \leq \pi$. See the plot on the next page.

(c)

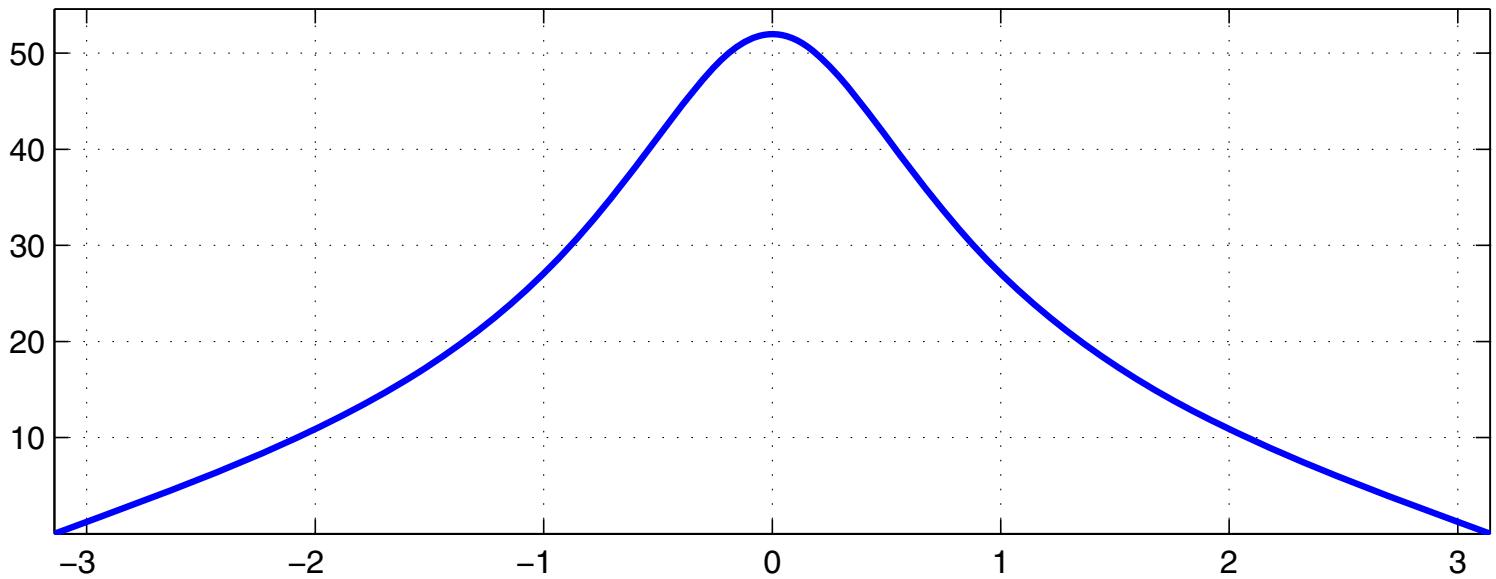
```
tt = 1e-12 + 0.02*(-100:100); %-avoid divide by zero
ht = sin(pi*tt)./tt/2;
plot(tt, ht)
```

Plot $\frac{\sin(\pi t)}{2t}$ for $-2 \leq t \leq 2$. See the plot on the next page.

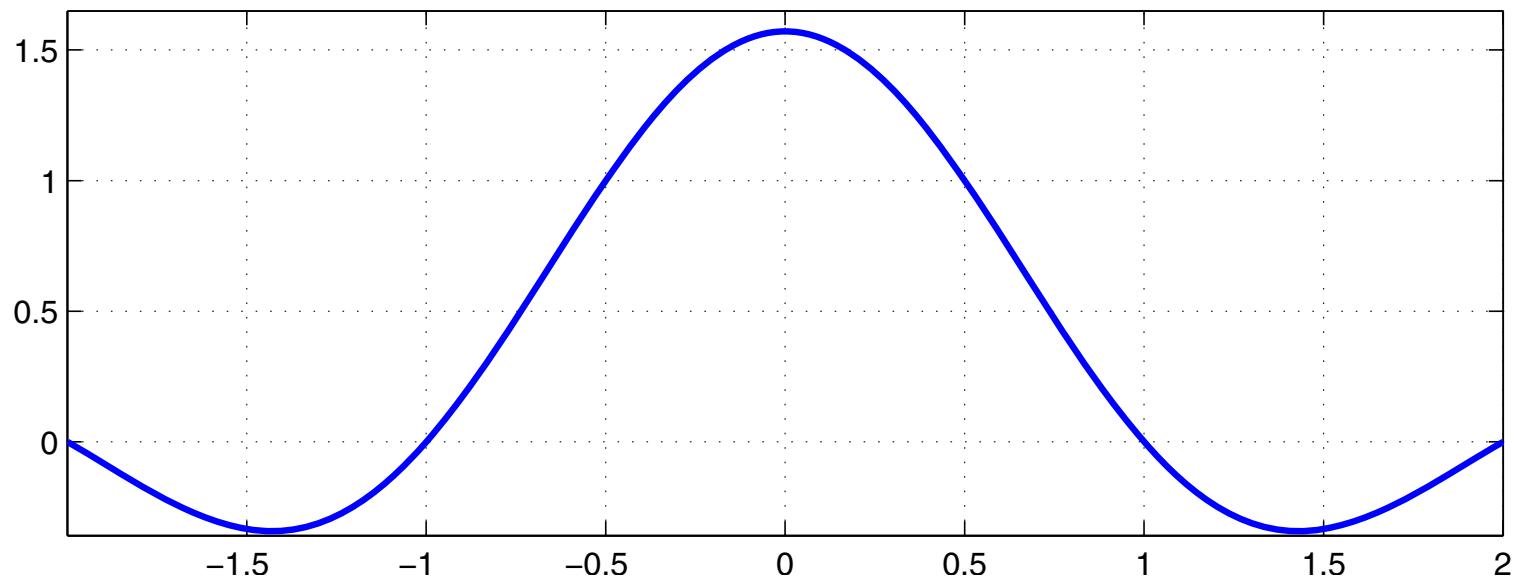
stem(yn=filter)



plot(HH=freekz)



plot(sinc vs. t)



PROBLEM sp-05-F.6:

In each of the following cases, determine the (inverse or forward) Fourier transform. The following Fourier transform pair will be needed for some parts:

$$x(t) = e^{-t^2} \leftrightarrow X(j\omega) = \sqrt{2\pi} e^{-\omega^2/4}$$

Give your answer as a plot, or a simple formula.

- (a) Find $x(t)$ when $X(j\omega) = 14 \cos(3\omega)$.

$$X(j\omega) = 7e^{j3\omega} + 7e^{-j3\omega}$$

$$\text{use } e^{-j\omega t_d} \longleftrightarrow \delta(t - t_d)$$

$$x(t) = 7\delta(t+3) + 7\delta(t-3)$$

- (b) Find $S(j\omega)$ when $s(t) = \left\{ \frac{d}{dt} e^{-t^2} \right\} \delta(t-3)$.

$$\frac{d}{dt} e^{-t^2} = -2te^{-t^2} \quad \text{eval at } t=3.$$

$$s(t) = (-2te^{-t^2})\delta(t-3) = -6e^{-9}\delta(t-3)$$

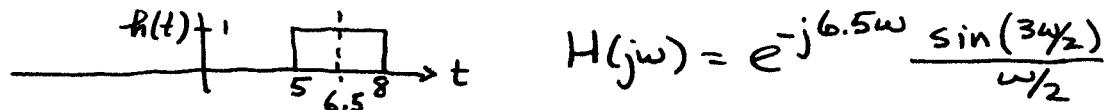
$$S(j\omega) = -6e^{-9}e^{-j3\omega}$$

- (c) Find $R(j\omega)$ when $r(t) = e^{-9t^2} = e^{-(3t)^2}$

$$\text{Use scaling property: } x(at) \leftrightarrow \frac{1}{|a|} X(j\omega/a) \quad a=3$$

$$R(j\omega) = \frac{1}{3} \sqrt{2\pi} e^{-(\omega/3)^2/4} = \frac{\sqrt{2\pi}}{3} e^{-\omega^2/36}$$

- (d) Find $H(j\omega)$ when $h(t) = u(t-5)u(8-t)$.



rect \leftrightarrow sinc
delayed by 6.5 duration of pulse = 3 secs.

- (e) The convolution $y(t) = \frac{\sin(13\pi t)}{\pi t} * \left\{ \sum_{n=-\infty}^{\infty} \delta(t - n/8) \right\}$ evaluates to a constant, i.e., $y(t) = y_0$.

Find the value of y_0 .

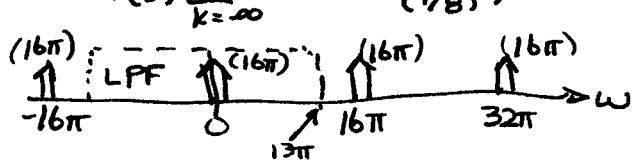
F.T. of impulse train is $2\pi(8) \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{2\pi k}{(1/8)})$

F.T. of $\frac{\sin(13\pi t)}{\pi t}$

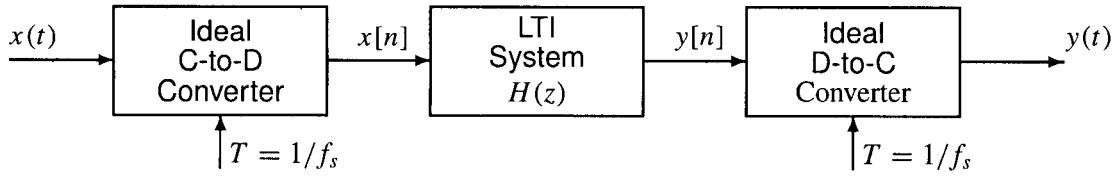
is L.P.F. cutoff $\pm 13\pi$

$\Rightarrow Y(j\omega) = 16\pi \delta(\omega)$

$$\Rightarrow y(t) = 8 = y_0$$



PROBLEM sp-05-F.7:



In all parts below, the sampling rates of the C-to-D and D-to-C converters are equal to $f_s = 180$ samples/sec, and the LTI system is an IIR filter with two poles at $0.9e^{\pm j\pi/3}$, and two zeros at $e^{\pm j\pi/3}$, i.e., the system function is $H(z) = \frac{(1 - q_1 z^{-1})(1 - q_2 z^{-1})}{(1 - p_1 z^{-1})(1 - p_2 z^{-1})}$, where $p_{1,2}$ are the poles and $q_{1,2}$ are the zeros.

- (a) Determine the filter coefficients of the IIR filter and fill in the IIR difference equation below.

$$y[n] = [0.9]y[n-1] + [-.81]y[n-2] + [1]x[n] + [-1]x[n-1] + [1]x[n-2]$$

$$H(z) = \frac{(1 - e^{j\pi/3}z^{-1})(1 - e^{-j\pi/3}z^{-1})}{(1 - 0.9e^{j\pi/3}z^{-1})(1 - 0.9e^{-j\pi/3}z^{-1})} = \frac{1 - z^{-1} + z^{-2}}{1 - 0.9z^{-1} + 0.81z^{-2}}$$

- (b) Determine the DC response of the digital filter, i.e., the output $y[n]$ when the input is $x[n] = 1$.

DC is $H(e^{j0})$, or $H(z)$ at $z = 1$

$$H(1) = \frac{1 - 1 + 1}{1 - 0.9 + 0.81} = 1.0989$$

- (c) If the input signal is a sinusoid of the form $x(t) = \cos(2\pi f_0 t + \phi)$, and the sampling rates are $f_s = 180$ samples/sec, determine a value for the input frequency f_0 so that the output signal is zero. *Explain.*

$$f_0 = [30] \text{ Hz}$$

The filter will null out $\hat{\omega} = \pi/3$

$$\text{Also, } \hat{\omega} = \frac{2\pi f}{f_s} \Rightarrow f = \frac{\hat{\omega} f_s}{2\pi}$$

$$\Rightarrow f_0 = \frac{(\pi/3)180}{2\pi} = 30 \text{ Hz}$$