

$$h_{bp}(t) = \left[\delta(t) - \frac{\sin(\omega_{c1}t)}{\pi t} \right] * \frac{\sin(\omega_{c2}t)}{\pi t}$$

$\delta(t)$ → F.T. → 1
 $\frac{\sin(\omega_{c1}t)}{\pi t}$ → Rectangle
 $\frac{\sin(\omega_{c2}t)}{\pi t}$ → (F.T) Rectangle.

1 - Rectangle

Convolution becomes multiplication in freq. domain

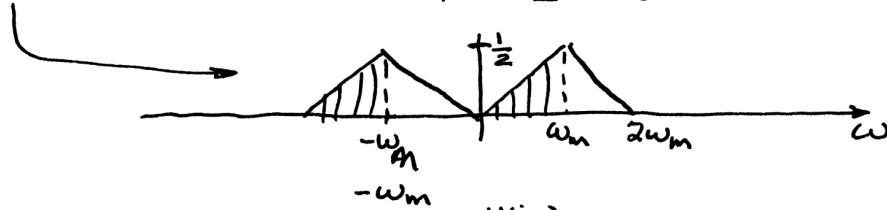
Multiply $(1 - \text{Rect}_1) \cdot \text{Rect}_2$

Only get 1 for $\omega > \omega_{c1}$ and $\omega < \omega_{c2}$

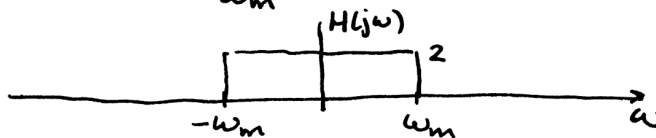


Problem 11.2:

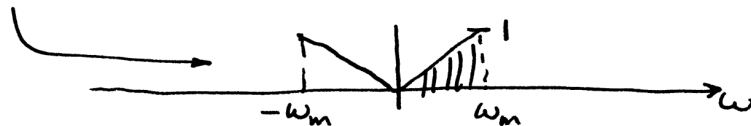
(a) $V(j\omega) = \frac{1}{2} X(j(\omega - \omega_m)) + \frac{1}{2} X(j(\omega + \omega_m))$



(b)

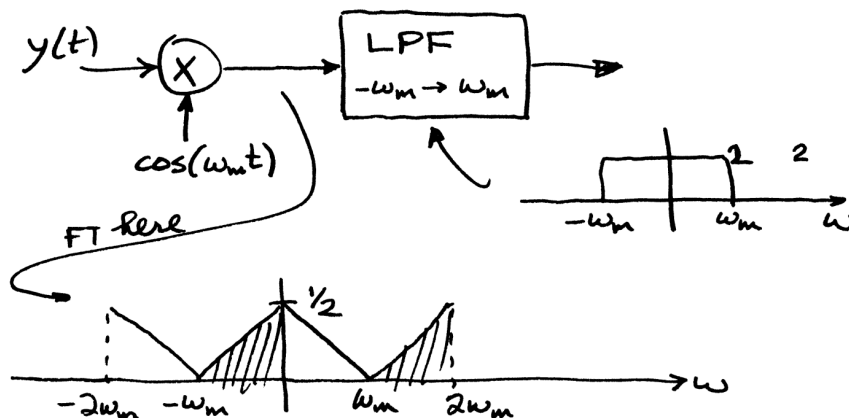


$Y(j\omega) = H(j\omega)V(j\omega)$



- (c) The negative-frequency components are moved into the positive frequency region, and vice versa. Also, the high-frequency components are moved to the low frequency region (near $\omega=0$). Likewise, low frequency components are moved to the high frequency region.

(d) Demodulator would be



To recover $x(t)$ we need an ideal LPF that will extract the spectrum from $-\omega_m$ to ω_m .

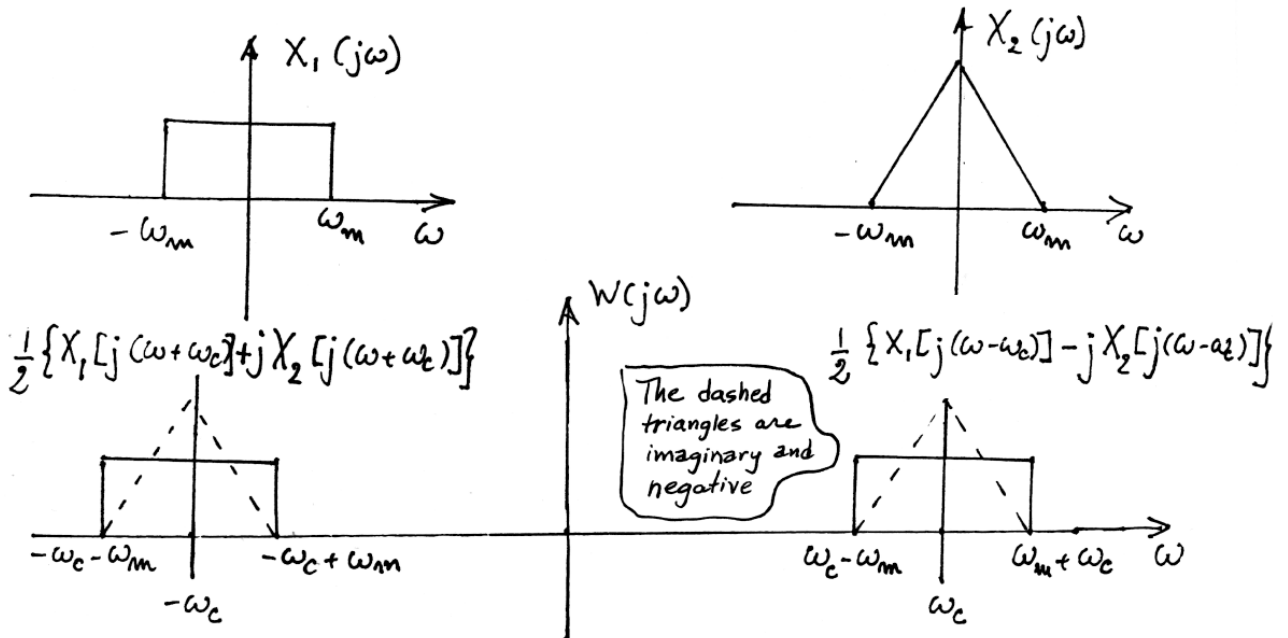
Problem 11.3:

$$a) \quad x_1(t) \cos(\omega_c t) \leftrightarrow \frac{1}{2} X_1[j(\omega - \omega_c)] + \frac{1}{2} X_1[j(\omega + \omega_c)]$$

$$x_2(t) \sin(\omega_c t) \leftrightarrow \frac{1}{2j} X_2[j(\omega - \omega_c)] - \frac{1}{2j} X_2[j(\omega + \omega_c)]$$

$$w(t) = x_1(t) \cos(\omega_c t) + x_2(t) \sin(\omega_c t) \leftrightarrow$$

$$W(j\omega) = \frac{1}{2} \{ X_1[j(\omega - \omega_c)] - j X_2[j(\omega - \omega_c)] \} + \\ + \frac{1}{2} \{ X_1[j(\omega + \omega_c)] + j X_2[j(\omega + \omega_c)] \}$$



Problem 11.3 (more):

$$b) \omega_a = \omega_c - \omega_m$$

$$\omega_b = \omega_c + \omega_m$$

$$c) v(t) = w(t) \sin(\omega_c t) = X_1(t) \sin(\omega_c t) \cos(\omega_c t) +$$

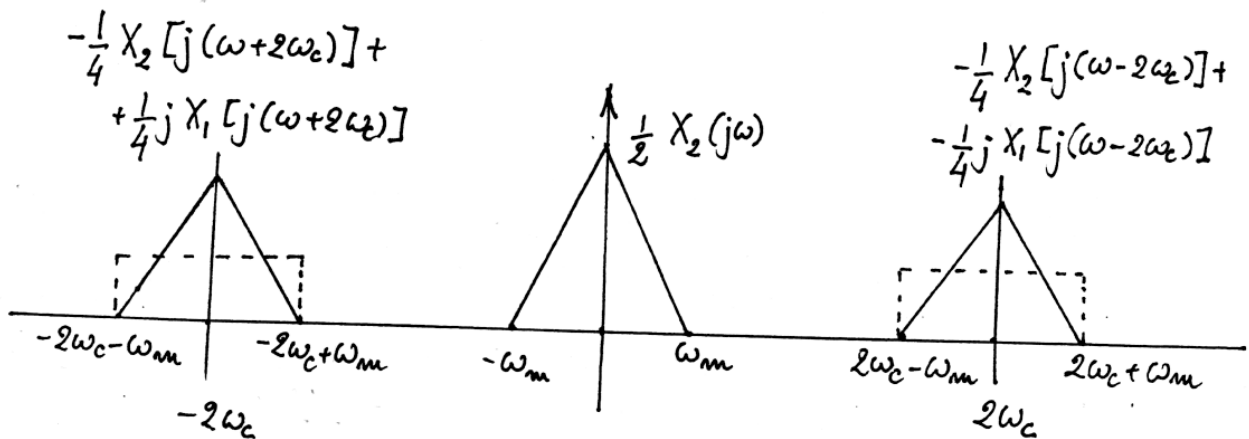
$$+ X_2(t) \sin^2(\omega_c t) = \frac{1}{2} X_1(t) \sin(2\omega_c t) +$$

$$+ \frac{1}{2} X_2(t) [1 - \cos(2\omega_c t)] = \frac{1}{2} X_2(t) +$$

$$+ \frac{1}{2} X_1(t) \sin(2\omega_c t) - \frac{1}{2} X_2(t) \cos(2\omega_c t)$$

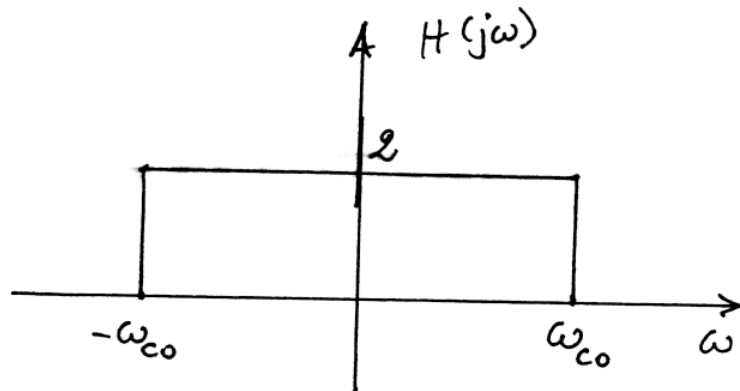
$$V(j\omega) = \frac{1}{2} X_2[j\omega] + \frac{1}{4j} \{ X_1[j(\omega - 2\omega_c)] +$$

$$- X_1[j(\omega + 2\omega_c)] \} - \frac{1}{4} \{ X_2[j(\omega - 2\omega_c)] + X_2[j(\omega + 2\omega_c)] \}$$



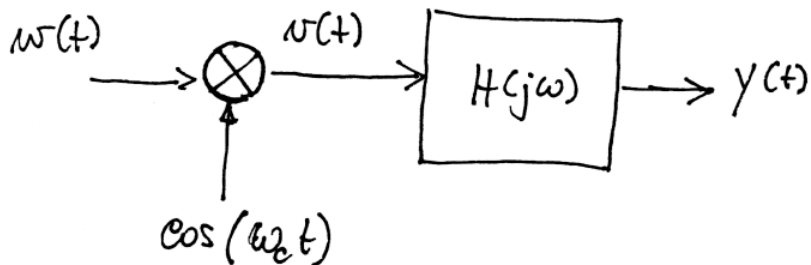
Problem 11.4:

d)



Ideal low-pass filter with gain equal to 2 and $\omega_m \leq \omega_{co} \leq 2\omega_c - \omega_m$ (in fact, a non-ideal low-pass filter will also work).

e)



$$\begin{aligned}
 v(t) &= x_1(t) \cos^2(\omega_c t) + x_2(t) \sin(\omega_c t) \cos(\omega_c t) = \\
 &= \frac{1}{2} x_1(t) [1 + \cos(2\omega_c t)] + \frac{1}{2} x_2(t) \sin(2\omega_c t) = \\
 &= \frac{1}{2} x_1(t) + \frac{1}{2} x_1(t) \cos(2\omega_c t) + \frac{1}{2} x_2(t) \sin(2\omega_c t)
 \end{aligned}$$

Problem 11.5:

$$a) \quad \cos \alpha \cos \beta = \frac{\cos(\alpha + \beta) + \cos(\alpha - \beta)}{2}$$

$$\cos(\omega_c t) \cos(\omega_c t + \phi) = \frac{1}{2} \cos(2\omega_c t + \phi) + \frac{1}{2} \cos \phi$$

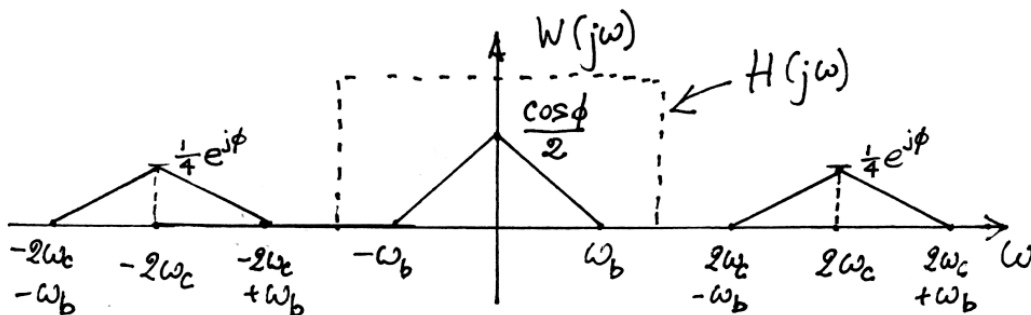
$$w(t) = x(t) \cos(\omega_c t + \phi) \cos(\omega_c t) =$$

$$= \frac{1}{2} x(t) \cos(2\omega_c t + \phi) + \frac{1}{2} x(t) \cos \phi =$$

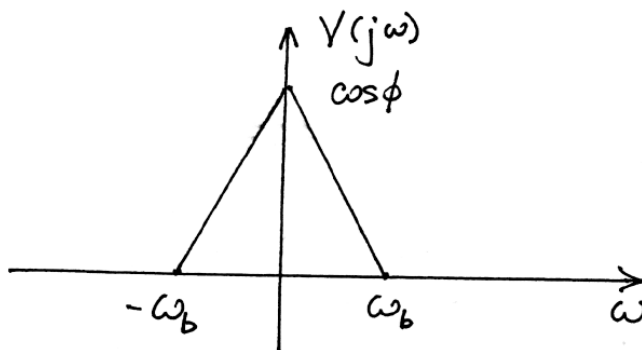
$$= \frac{1}{4} x(t) e^{j\phi} e^{j2\omega_c t} + \frac{1}{4} x(t) e^{-j\phi} e^{-j2\omega_c t} + \frac{1}{2} x(t) \cos \phi$$

b)

$$W(j\omega) = \frac{1}{4} e^{j\phi} X[j(\omega - 2\omega_c)] + \frac{1}{4} e^{-j\phi} X[j(\omega + 2\omega_c)] + \frac{\cos \phi}{2} X(j\omega)$$



c)



$$d) \quad w(t) = x(t) \cos \phi$$