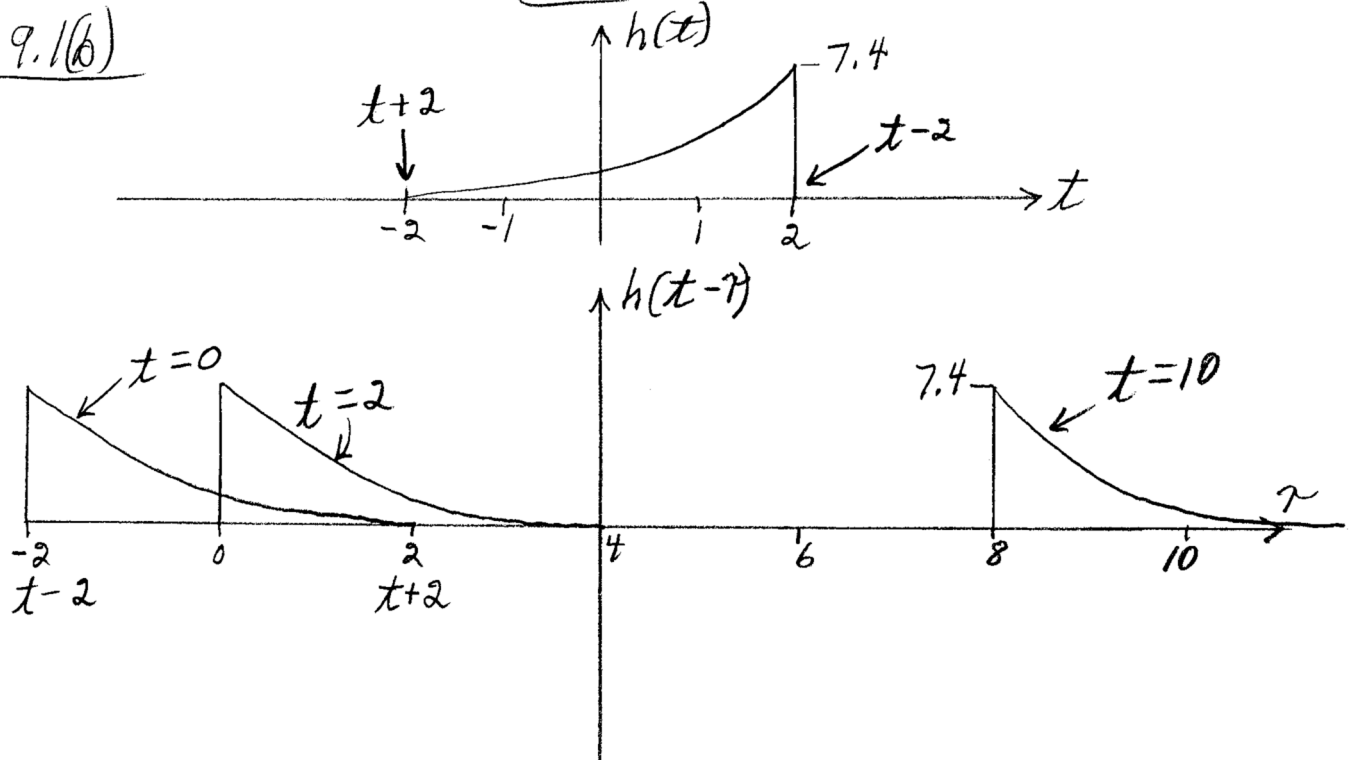


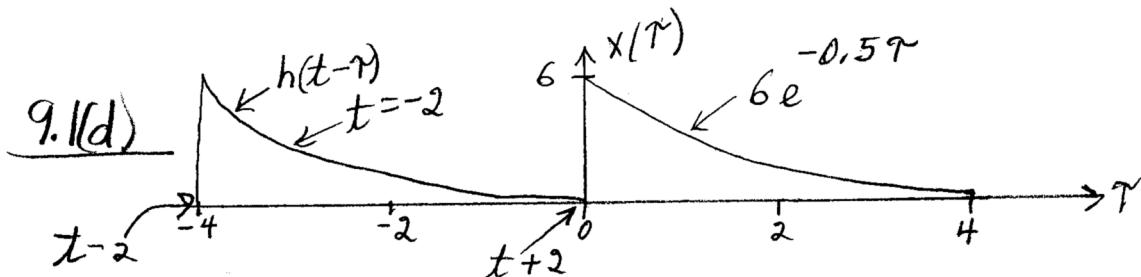
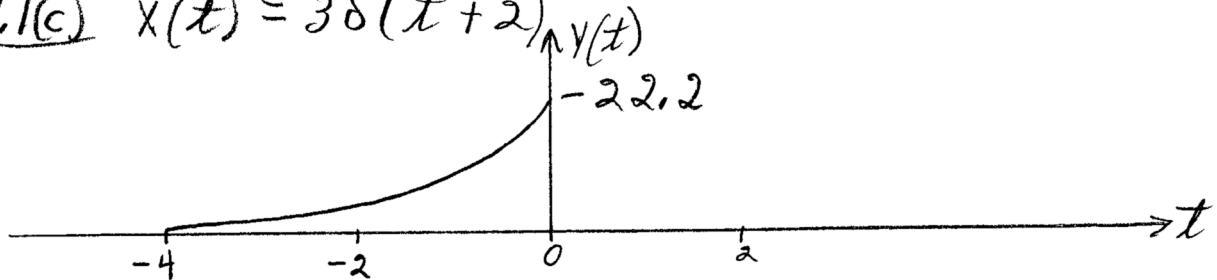
9.1(a)  $h(t) = e^{0.5t} [u(t+2) - u(t-2)]$

↑  
NOT causal

9.1(b)



9.1(c)  $x(t) = 3\delta(t+2)$



There are 4 regions:

$t < -2$	$y_1(t) = 0$	①
$-2 < t < 2$	$y_2(t) = ?$	②
$2 < t < 6$	$y_3(t) = ?$	③
$6 < t$	$y_4(t) = 0$	④

**Problem 9.1(d):** A linear time-invariant system has impulse response:

$$h(t) = e^{0.5t} \{u(t+2) - u(t-2)\} = \begin{cases} e^{0.5t} & -2 \leq t < 2 \\ 0 & \text{otherwise} \end{cases}$$

Use the convolution integral to determine the output  $y(t)$  when the input is

$$x(t) = 6e^{-0.5t} \{u(t) - u(t-4)\} = \begin{cases} 6e^{-0.5t} & 0 \leq t < 4 \\ 0 & \text{otherwise} \end{cases}$$

There are normally 5 regions when you convolve two finite-duration signals. In this case, the complete overlap region is just a point because both signals have a length of 4 secs, so there are only 4 regions to consider:

Region 1: No overlap for  $t < -2$ , so  $y(t) = 0$ .

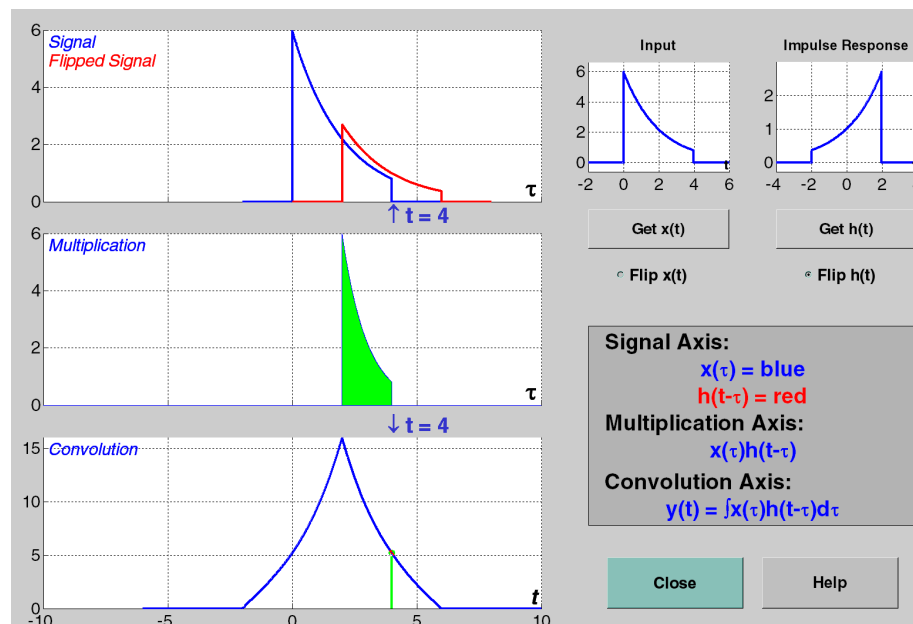
Region 2: **Partial** overlap for  $-2 \leq t < 2$ ; in this region the output signal is:

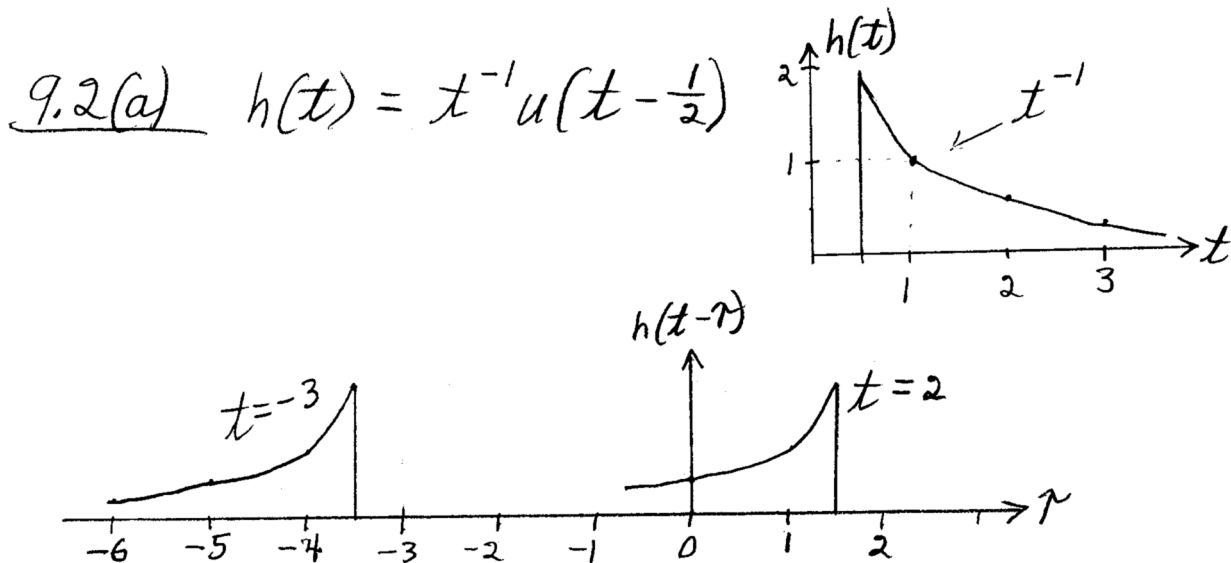
$$\begin{aligned} y(t) &= \int_0^{t+2} e^{-0.5\tau} 6e^{0.5(t-\tau)} d\tau \\ &= 6e^{0.5t} \int_0^{t+2} e^{-\tau} d\tau = -6e^{0.5t} e^{-\tau} \Big|_0^{t+2} = 6e^{0.5t} (e^0 - e^{-(t+2)}) = 6e^{0.5t} - 6e^{-0.5t-2} \end{aligned}$$

Region 3: **Partial** overlap for  $2 \leq t \leq 6$ ; in this region the output signal is:

$$\begin{aligned} y(t) &= \int_{t-2}^4 e^{-0.5\tau} 6e^{0.5(t-\tau)} d\tau \\ &= 6e^{0.5t} \int_{t-2}^4 e^{-\tau} d\tau = -6e^{0.5t} e^{-\tau} \Big|_{t-2}^4 = 6e^{0.5t} (e^{-(t-2)} - e^{-4}) = 6e^{-0.5t+2} - 6e^{0.5t-4} \end{aligned}$$

Region 4: No overlap for  $t > 6$ , so  $y(t) = 0$ .

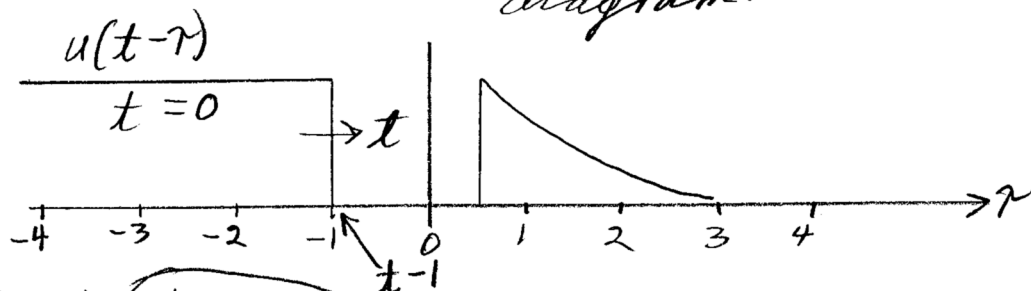




9.2(b) Yes,  $h(t)$  is causal, because there is no output before input.

9.2(c) No  $h(t)$  is not stable  
 $\int_{0.5}^{\infty} t^{-1} dt = \ln \infty - \ln 0.5$  which is not bounded.

9.2(d)  $x(t) = u(t-1)$  Draw the convolution diagram.



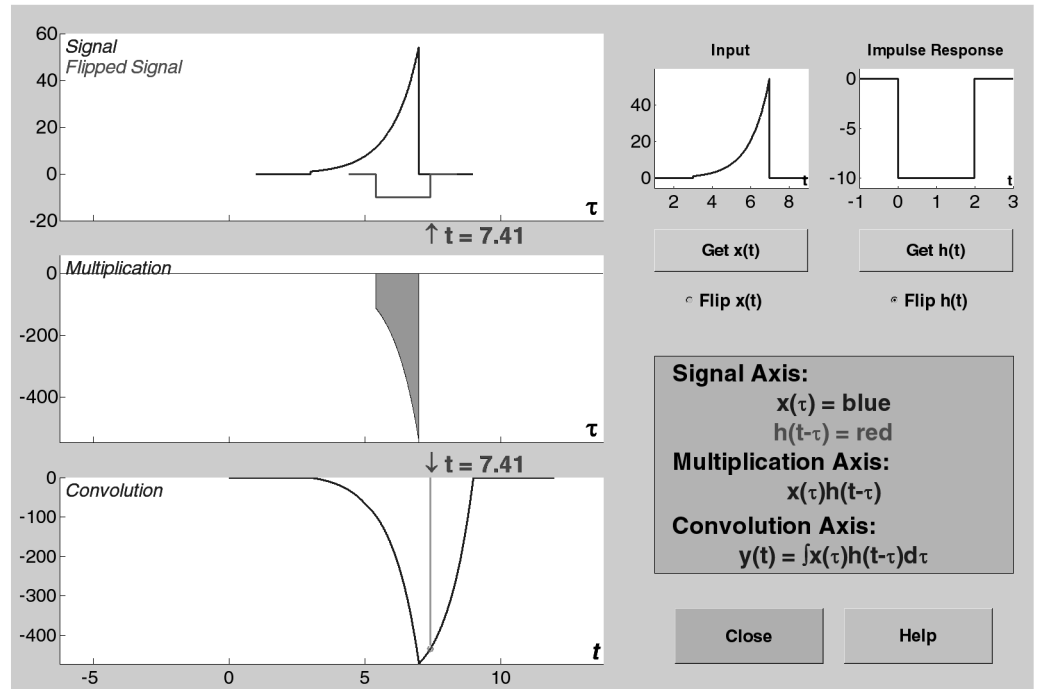
Clearly  $t_1 = 1.5$

9.2(e)  $y(t) = \int_{\tau=0.5}^{\tau=t-1} \tau^{-1} d\tau = \ln \tau \Big|_{0.5}^{t-1} = \ln(t-1) - \ln 0.5$

$= \ln[2(t-1)]$

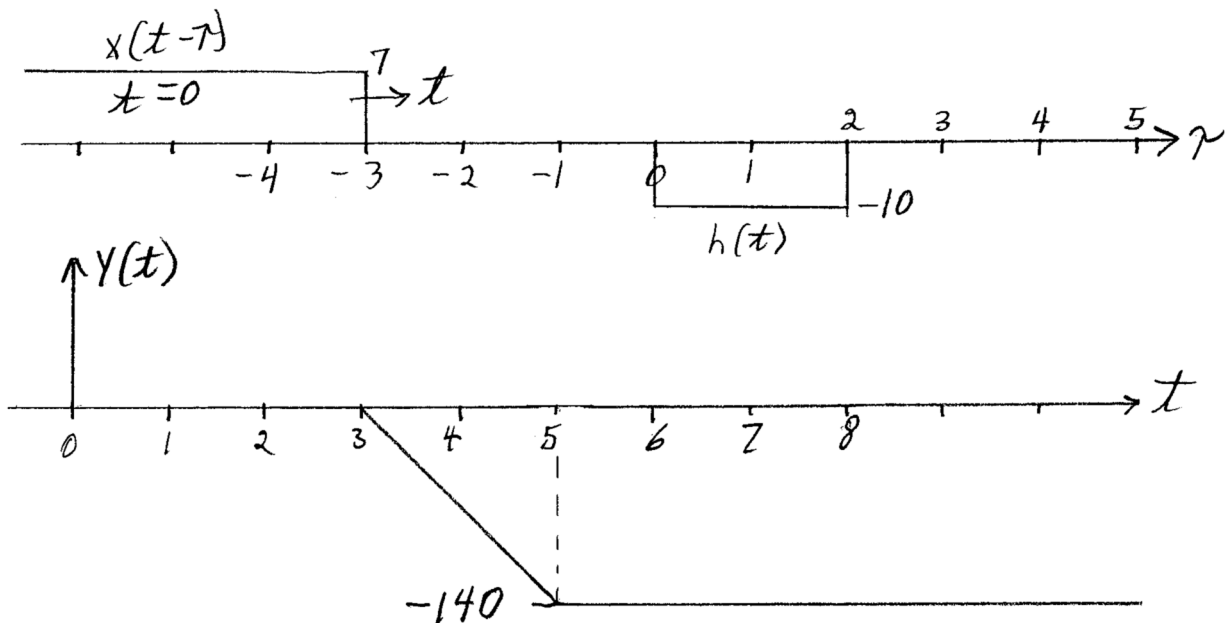
9.3(a)

$$\text{Duration} = 9 - 3 = 6$$



9.3(b) The min value of  $y(t)$  occurs when  $t = 7$

$$\text{9.3(c)} \quad x(t) = 7u(t-3) \quad h(t) = 10[u(t-2) - u(t)]$$



$$y(t) = \underset{-70}{B}(t - \underset{3}{T_{12}}) \left[ \underset{3}{u(t - T_{12})} - \underset{5}{u(t - T_{23})} \right] + \underset{-140}{C} \underset{5}{u(t - T_{23})}$$

$$B = -70 \quad T_{12} = 3 \quad C = -140 \quad T_{23} = 5$$

9.4  $h_1(t) = e^{-t} u(t - \frac{1}{2})$   $y(t) = \frac{d}{dt} w(t-2) - \int_{-\infty}^{t-2} w(\tau) d\tau$

9.4(a)

If  $x(t) = \delta(t)$ , then  $y(t) = h_1(t) * h_2(t)$ , which is the overall system impulse response,  $h(t)$ . Therefore

$$y(t) \Big|_{x(t)=\delta(t)} = \frac{d}{dt} \left[ e^{-(t-2)} u(t-2.5) \right] - \int_{-\infty}^{t-2} e^{-\tau} u(\tau - \frac{1}{2}) d\tau$$

$$= -e^{-(t-2)} u(t-2.5) + e^{-(t-2)} \delta(t-2.5) - \int_{\tau=\frac{1}{2}}^{t-2} e^{-\tau} d\tau$$

The integral is only valid for  $t-2 \geq 0.5$ .  $\therefore t \geq 2.5$

$$= e^{-0.5} e^{-(t-2.5)} \delta(t-2.5) - e^{-0.5} e^{-(t-2.5)} u(t-2.5)$$

$$+ e^{-\tau} \Big|_{\frac{1}{2}}^{t-2} u(t-2.5)$$

$$= e^{-0.5} e^{-(t-2.5)} \delta(t-2.5) - e^{-0.5} e^{-(t-2.5)} u(t-2.5)$$

$$+ \left( \frac{e^{-0.5} e^{-(t-2.5)}}{e^{-0.5} e^{-0.5}} - e^{-0.5} \right) u(t-2.5)$$

$$= e^{-0.5} e^0 \delta(t-2.5) - e^{-0.5} u(t-2.5)$$

$$= e^{-0.5} \delta(t-2.5) - e^{-0.5} u(t-2.5)$$

9.4(b)  $x(t) = e^t u(t)$

$$y(t) = x(t) * h(t) = \left[ e^t u(t) \right] * e^{-0.5t} \left[ \delta(t-2.5) - u(t-2.5) \right]$$

$$= e^{-0.5t} \left[ e^t u(t) \right] * \left[ \delta(t-2.5) - u(t-2.5) \right]$$

$$= e^{-0.5t} \left[ e^{(t-2.5)} u(t-2.5) \right] - e^{-0.5t} \left[ e^t u(t) * u(t-2.5) \right]$$

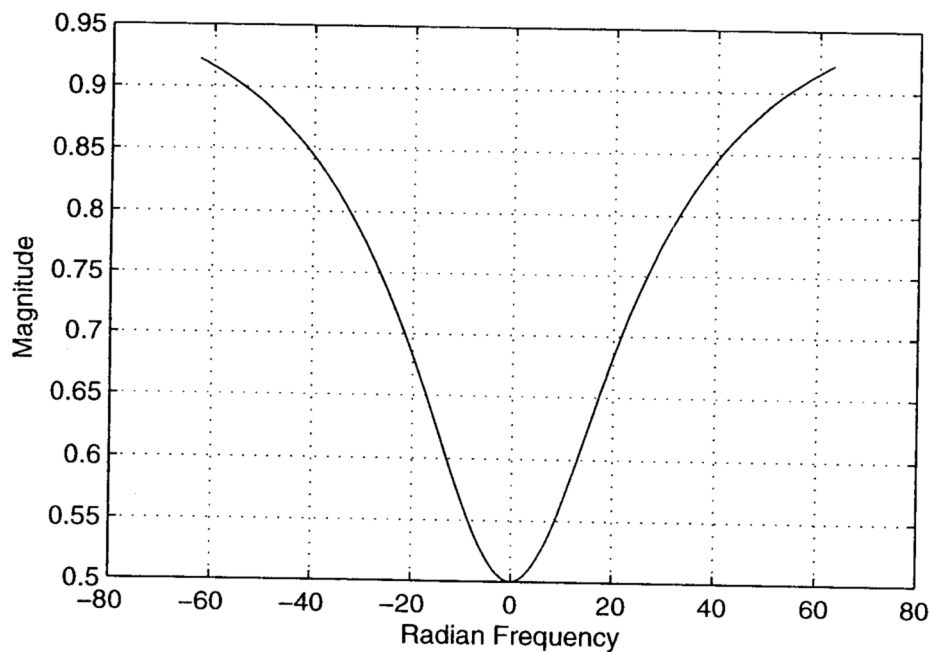
$$= e^{-0.5t} e^{(t-2.5)} u(t-2.5) - e^{-0.5t} \left[ e^{(t-2.5)} u(t-2.5) - u(t-2.5) \right]$$

$$= e^{-0.5t} u(t-2.5)$$

9.5  $h(t) = \delta(t) - \frac{1}{2} b e^{-bt} u(t)$

9.5(a)  $H(\omega) = 1 - \frac{b/2}{b + j\omega}$  using the table of basic transform pairs

9.5(b) for  $b = 10\pi$ ,  $H(\omega) = 1 - \frac{5\pi}{10\pi + j\omega}$



9.5(c) The filter is a HPF.

9.5(d)  $x(t) = 10 + 40 \cos(90\pi t)$   
 $H(\omega=0) = 0.5$   $H(\omega=90\pi) = 0.9954 e^{j0.0552}$

$$\begin{aligned} x(t) &= 10(0.5) + 40(0.9954) \cos(90\pi t + 0.0552) \\ &= 5 + 39.816 \cos(90\pi t + 0.0552) \end{aligned}$$