

**ECE2025 Fall 2003**  
**Solution of Problem Set #2**

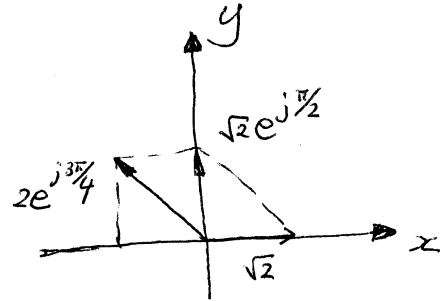
**Problem 2.1**

(a)

$$x_a(t) = 2 \cos(100\pi t + 3\pi/4) + \sqrt{2} \cos(100\pi t)$$

$$\begin{aligned} \Downarrow \\ X &= 2e^{j3\pi/4} + \sqrt{2} \\ &= j\sqrt{2} \\ &= \sqrt{2}e^{j\pi/2} \end{aligned}$$

$$\Downarrow \\ x_a(t) = \sqrt{2} \cos(100\pi t + \pi/2)$$

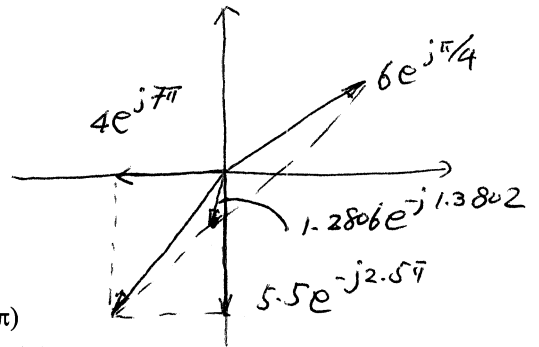


(b)

$$x_b(t) = 4 \cos(2000\pi t + 7\pi) + 5.5 \cos(2000\pi t - 2.5\pi) - 6 \cos(2000\pi t - 3\pi/4)$$

$$\begin{aligned} \Downarrow \\ X &= 4e^{j7\pi} + 5.5e^{-j2.5\pi} - 6e^{-j3\pi/4} \\ &\approx 0.2426 - j1.2574 \\ &\approx 1.2806e^{-j1.3802} \end{aligned}$$

$$\Downarrow \\ x_b(t) = 1.280 \cos(100\pi t - 1.3802)$$

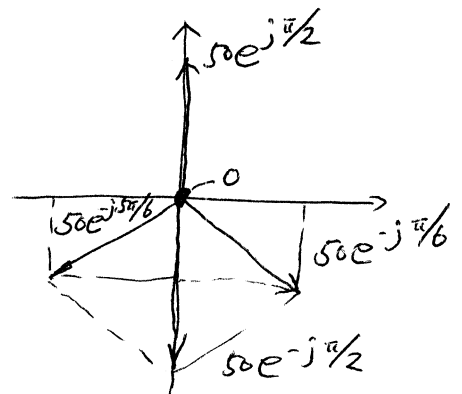


(c)

$$\begin{aligned} x_b(t) &= 50 \cos(120\pi t - \pi/6) + 50 \cos(120\pi t - 5\pi/6) + 50 \sin(120\pi t + \pi) \\ &= 50 \cos(120\pi t - \pi/6) + 50 \cos(120\pi t - 5\pi/6) + 50 \cos(120\pi t + \pi/2) \end{aligned}$$

$$\begin{aligned} \Downarrow \\ X &= 50e^{-j\pi/6} + 50e^{-j5\pi/6} + 50e^{j\pi/2} \\ &\approx 0 \end{aligned}$$

$$\Downarrow \\ x_c(t) = 0$$

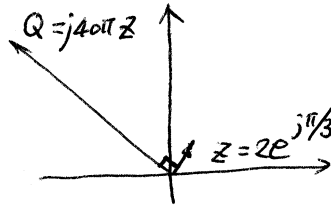


**Problem 2.2**

(a)

$$\begin{aligned} \frac{d}{dt} z(t) &= \frac{Z \cdot (j40\pi)}{Q} \cdot e^{j40\pi t} \\ &= Qe^{j40\pi t} \\ Q &= Z \cdot (j40\pi) \\ &= 40\pi e^{j\pi/2} Z \\ &= 80\pi e^{j5\pi/6} \end{aligned}$$

(b) The angle of Q is  $\pi/2$  greater than that of Z. It is also shown by the following figure.



(c) Since  $z(t) = 2e^{j(40\pi t + \pi/3)}$  and

$$\begin{aligned}\Re\left\{\frac{d}{dt}z(t)\right\} &= \Re\left\{j40\pi \cdot 2e^{j(40\pi t + \pi/3)}\right\} \\ &= -80\pi \sin(40\pi t + \pi/3) \\ \frac{d}{dt}\Re\{z(t)\} &= \frac{d}{dt}2\cos(40\pi t + \pi/3) \\ &= -40\pi \cdot 2\sin(40\pi t + \pi/3) \\ &= \Re\left\{\frac{d}{dt}z(t)\right\}\end{aligned}$$

It is true for all complex exponential signals.

(d)

$$\begin{aligned}\int_{-0.05}^{0.05} z(t) dt &= \int_{-0.05}^{0.05} Ze^{j40\pi t} dt \\ &= \frac{1}{j40\pi} Ze^{j40\pi t} \Big|_{t=-0.05}^{0.05} \\ &= \frac{1}{j40\pi} Ze^{j40\pi \cdot 0.05} - \frac{1}{j40\pi} Ze^{j40\pi \cdot (-0.05)} \\ &= 0\end{aligned}$$

(e)

$$\begin{aligned}z(t - t_d) &= Ze^{j40\pi(t - t_d)} \\ &= \underbrace{Ze^{-j40\pi t_d}}_P e^{j40\pi t} \\ P &= Ze^{-j40\pi t_d} = 2e^{-j40\pi t_d + j\pi/3}\end{aligned}$$

$z(t - t_d) = z(t)$  if and only if  $e^{-j40\pi t_d} = 1$  or  $40\pi t_d = 2\pi k$  for any integer  $k$ , that is,  $t_d = k/20$  for  $k = 0, \pm 1, \pm 2, \dots$ .

### Problem 2.3

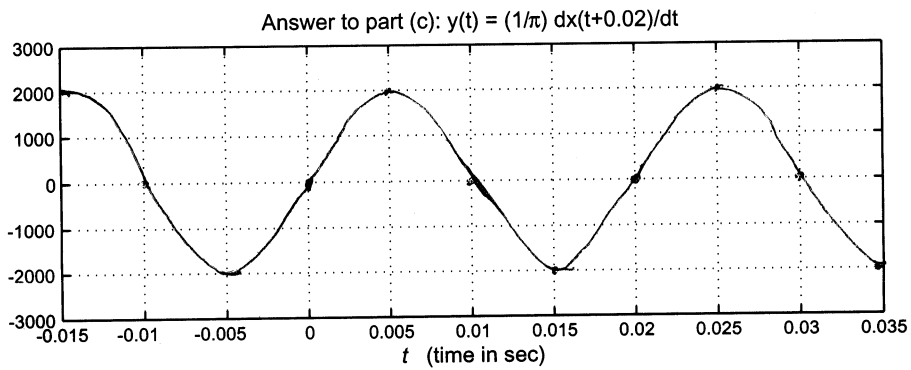
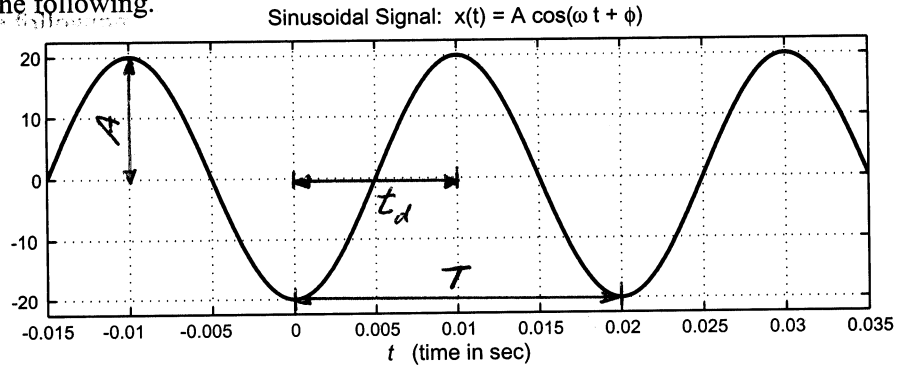
(a) From the figure, we can see that  $A = 20$ ,  $t_d = 0.01$  sec, and  $T = 0.02$ . Therefore,

$$\begin{aligned}\omega_o &= \frac{2\pi}{T} = \frac{2\pi}{0.02} = 100\pi, \\ \phi &= -\omega_o t_d = -100\pi \cdot 0.01 = -\pi, \\ x(t) &= 20 \cos(100\pi t - \pi).\end{aligned}$$

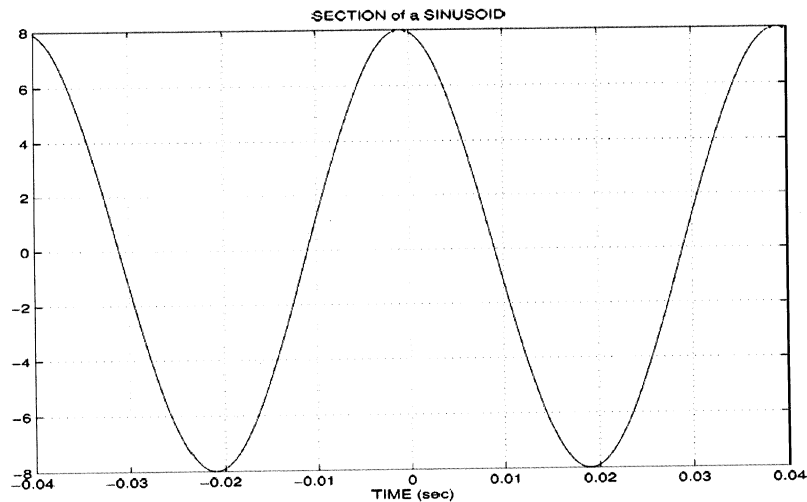
(b)

$$\begin{aligned}x(t) &= 20 \cos(100\pi t - \pi) \\ &= \Re\{20e^{j(100\pi t - \pi)}\} \\ &= \Re\left\{\underbrace{20e^{-j\pi}}_Z e^{j100\pi t}\right\}, \\ Z &= 20e^{-j\pi}.\end{aligned}$$

(c)  $y(t) = \frac{1}{\pi} \frac{d}{dt} [x(t+0.02)] = \frac{1}{\pi} \frac{d}{dt} [20 \cos(100\pi(t+0.02) - \pi)] = 2000 \cos(100\pi t - \pi/2)$ . The figure is shown as the following.



**Problem 2.4**  $A = 8$ ,  $\omega_0 = 2\pi F_0$ ,  $T = 1/F_0 = 0.04$ , and  $\phi = \omega_0 t_d = 2\pi \cdot 25 \cdot 0.001 = 0.05\pi$ . The figure is as the following.



**Problem 2.5** Substitute  $a$  by  $j\theta$  in the Taylor series of  $\exp(a)$ , we have

$$\begin{aligned}\exp(j\theta) &= 1 + j\theta + \frac{(j\theta)^2}{2!} + \frac{(j\theta)^3}{3!} + \frac{(j\theta)^4}{4!} + \frac{(j\theta)^5}{5!} + \dots \\ &= 1 + j\theta - \frac{\theta^2}{2!} - j\frac{\theta^3}{3!} + \frac{\theta^4}{4!} + j\frac{\theta^5}{5!} + \dots \\ &= \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} + \dots\right) + j\left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} + \dots\right) \\ &= \cos(\theta) + j\sin(\theta),\end{aligned}$$

which proves Euler's formula.