

GEORGIA INSTITUTE OF TECHNOLOGY  
SCHOOL of ELECTRICAL and COMPUTER ENGINEERING

**ECE 2025    Fall 1999**  
**Problem Set #12**

Assigned: 12 Nov 99

Due Date: 19 Nov 99 (FRIDAY)

**Quiz #3 will be given on Monday, November 22 in your regular class time.**

Coverage: Material on Problem Sets #9, #10, #11 and #12.

Reading: Read Chapter 11 all, and Chapter 12, pp. 1200–1222 in Notes.

⇒ The five (5) **STARRED** problems will have to be turned in for grading.

Next week a solution will be posted. Some similar problems solutions can be found in the old problems from EE-2201 on Web-CT.

**PROBLEM 12.1\*:**

Try your hand at expressing each of the following in a simpler form:

(a)  $[e^{-t} \cos(2\pi t)][\delta(t) + 2\delta(t - 3)] =$

(b)  $[\delta(t) - u(t)] * [\delta(t - 1) + \delta(t - 2)] =$

(c)  $\int_{-\infty}^{\infty} \sin(2\pi\tau + \pi/3)\delta(t - \tau)d\tau =$

(d)  $\frac{d}{dt} [e^{-(t-1)}u(t - 1)] =$

**PROBLEM 12.2\*:**

A continuous-time linear time-invariant system has impulse response

$$h(t) = \delta(t) - 10e^{-10t}u(t).$$

- (a) Determine the frequency response  $H(j\omega)$  of the system. Express your answer as a rational function with powers of  $(j\omega)$  in the numerator and denominator.
- (b) Plot the magnitude squared,  $|H(j\omega)|^2 = H(j\omega)H^*(j\omega)$ , versus  $\omega$ . Likewise, plot the phase  $\angle H(j\omega)$  as a function of  $\omega$ .
- (c) Use superposition to find the output due to an input that is the sum of three terms:

$$x(t) = 100 + 20 \cos(10t) + \delta(t - 3).$$

*Hint: Use the easiest method (impulse response or frequency response) to find the output due to each component of the input.*

**PROBLEM 12.3\*:**

A continuous-time LTI system is defined by the following input/output relation:

$$y(t) = \frac{1}{2}x(t) + x(t - 4) + \frac{1}{2}x(t - 8). \quad (1)$$

- (a) Determine the impulse response  $h(t)$  of the overall system; i.e., determine the output when the input is an impulse.
- (b) Substitute your answer for  $h(t)$  into the the integral formula

$$H(j\omega) = \int_{-\infty}^{\infty} h(t)e^{-j\omega t} dt$$

to obtain the frequency response.

- (c) Apply the system definition given in Eq. (1) directly to the input  $x(t) = e^{j\omega t}$  for  $-\infty < t < \infty$  and show that  $y(t) = H(j\omega)e^{j\omega t}$ , where  $H(j\omega)$  is as determined in part (b).
- (d) Sketch the magnitude  $|H(j\omega)|$  and phase  $\angle H(j\omega)$  as functions of  $\omega$ .

**PROBLEM 12.4:**

*Attend Recitation to see how to do this problem.*

A *periodic impulse train* with period  $T_0$  is defined to be the signal

$$x(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_0).$$

- (a) Plot this signal for  $-3T_0 \leq t \leq 3T_0$ .
- (b) What is the fundamental frequency,  $\omega_0$  if  $T_0 = 10$ ? **Use  $T_0 = 10$  in all the following parts.**
- (c) Determine the Fourier coefficients  $a_k$  in the Fourier series representation

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}.$$

- (d) Plot the spectrum of this signal for  $-4\omega_0 \leq \omega \leq 4\omega_0$ .
- (e) The periodic impulse train  $x(t)$  is the input to a system with frequency response

$$H(j\omega) = \begin{cases} e^{-j\omega^4} & |\omega| < \omega_{co} \\ 0 & |\omega| > \omega_{co}. \end{cases}$$

Determine the output signal  $y(t)$  if  $\omega_{co} = \pi/T_0$ .

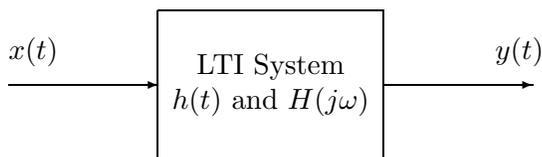
- (f) The periodic impulse train  $x(t)$  is the input to a system with frequency response

$$H(j\omega) = \begin{cases} e^{-j\omega^4} & |\omega| < \omega_{co} \\ 0 & |\omega| > \omega_{co}. \end{cases}$$

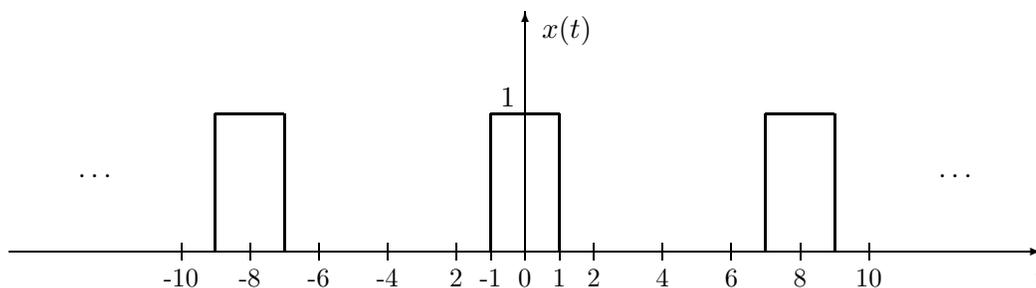
Determine the output signal  $y(t)$  if  $\omega_{co} = 3\pi/T_0$ .

**PROBLEM 12.5\*:**

Consider the LTI system below:



The input to this system is the periodic pulse wave  $x(t)$  depicted below:



- (a) Determine  $\omega_0$  and the coefficients  $a_k$  in the Fourier series representation of  $x(t)$ .

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$$

- (b) Plot the spectrum of the signal  $x(t)$ ; i.e., make a plot showing the  $a_k$ 's plotted at the frequencies  $k\omega_0$  for  $-4\omega_0 \leq \omega \leq 4\omega_0$ .
- (c) If the frequency response is  $H(j\omega) = e^{-j3\omega}$ , plot the output of the system  $y(t)$  when the input is  $x(t)$  as plotted above. *Hint: What simple system has this kind of frequency response?*
- (d) If the frequency response of the system is the ideal lowpass filter

$$H(j\omega) = \begin{cases} 1 & |\omega| < 0.5\pi \\ 0 & |\omega| > 0.5\pi \end{cases}$$

what is the output of the system when the input is  $x(t)$  as depicted above? Give a simple equation for  $y(t)$  as a real-valued function. *Use the plot of part (b) and a plot of the frequency response to help you solve this problem.*

**PROBLEM 12.6\*:**

Use the delay property of Fourier transforms,

$$x(t - t_d) \iff e^{-j\omega t_d} X(j\omega),$$

to determine the Fourier transforms of the following signals:

- (a)  $x(t) = \delta(t - 5)$
- (b)  $x(t) = 20 \frac{\sin(200\pi(t - 10))}{\pi(t - 10)}$
- (c)  $x(t) = e^{-4t}u(t) - e^{-4t}u(t - 10) = e^{-4t}u(t) - e^{-40}e^{-4(t-10)}u(t - 10)$